

ECE4902 Lecture 9

2-Stage Op-Amp

1st-2nd Stage: NMOS or PMOS?!?

DC Analysis

Input Common-Mode Range

Feedback

Stability

Handouts:

Lab 8/9 Review Slides

Differential Pair

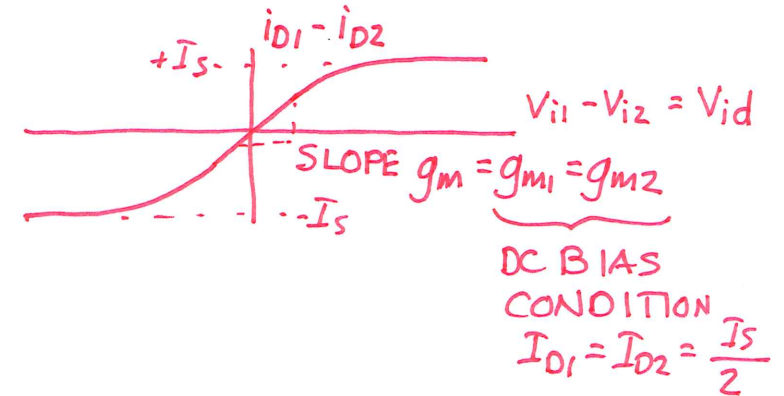
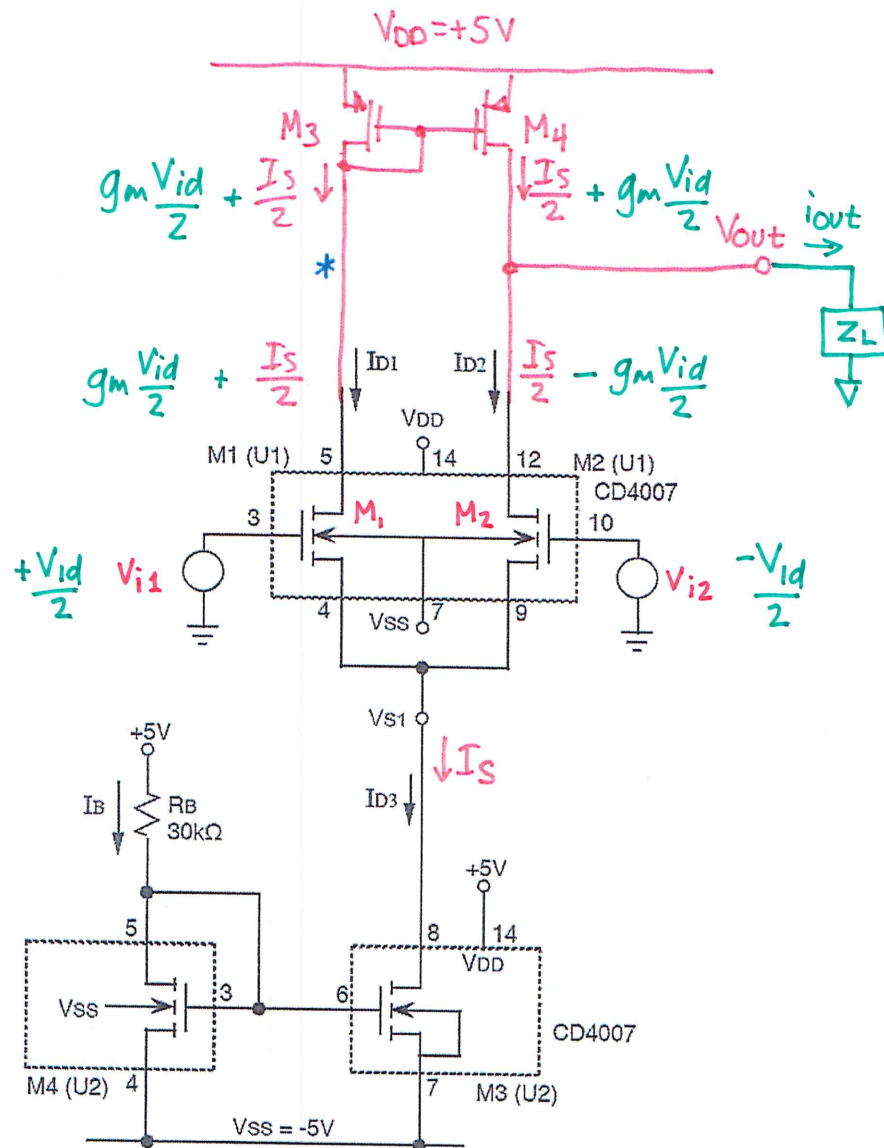
2nd Stage Common Source

Lab 8 Op-Amp

**THE MOST
IMPORTANT
LECTURE OF
~~ECE4902!~~
YOUR LIFE**

Differential Pair with Mirror Load: Single Ended Output; Recovering "Other" Half of Differential Signal

DIFF PAIR TRANSCONDUCTANCE (1/2 CIRCUIT)



SIGNAL: $V_{id} = V_{i1} - V_{i2}$

SYMMETRY: HALF AT EACH INPUT

M1: $+\frac{V_{id}}{2} \Rightarrow I_{D1} \uparrow$ HOW MUCH? $\frac{\Delta I_D}{\Delta V_{GS}} = g_m$

M2: $-\frac{V_{id}}{2} \Rightarrow I_{D2} \downarrow$

WHAT ABOUT M3, M4 MIRROR?

M3: SAME AS M1 I_{D1}

M4: MIRROR I_{D3} TO I_{D4}

KCL "DISAGREEMENT" AT V_{out} NODE!

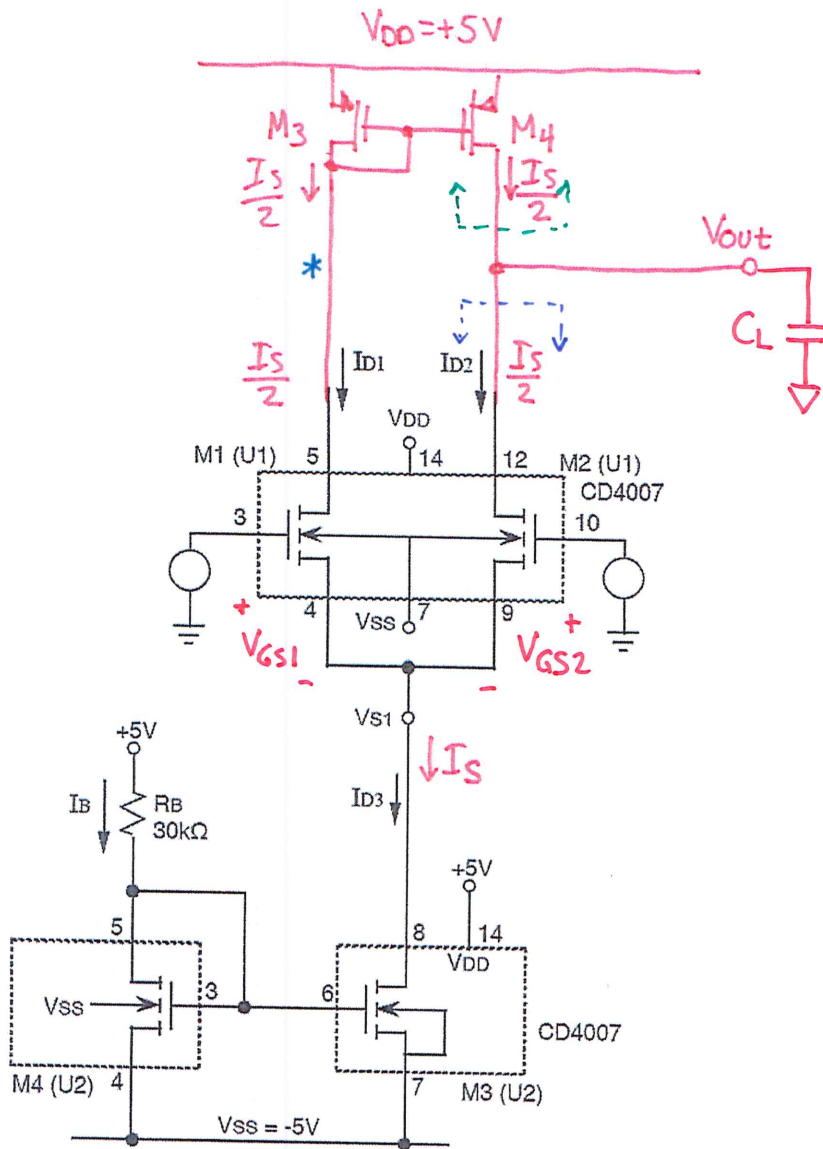
DIFFERENCE i_{out} FLOWS IN Z_L AT LOAD

KCL: $\frac{I_S}{2} + g_m \frac{V_{id}}{2} = \frac{I_S}{2} - g_m \frac{V_{id}}{2} + i_{out}$

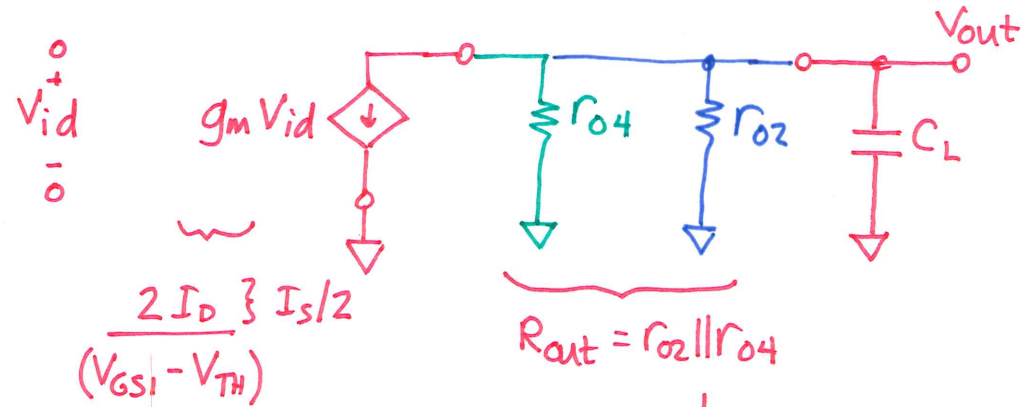
$g_m V_{id} = i_{out}$ } "RECOVER" "OTHER" HALF

$$V_{out} = i_{out} Z_L = g_m V_{id} Z_L \Rightarrow \boxed{\frac{V_{out}}{V_{id}} = g_m Z_L}$$

Differential Pair with Mirror Load: Small Signal Model



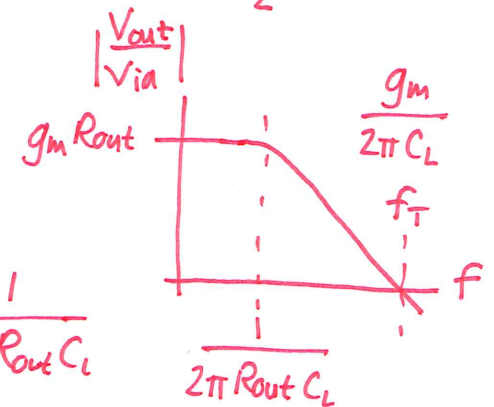
TRANSCONDUCTANCE
OF DIFF PAIR



TRANSFER FUNCTION

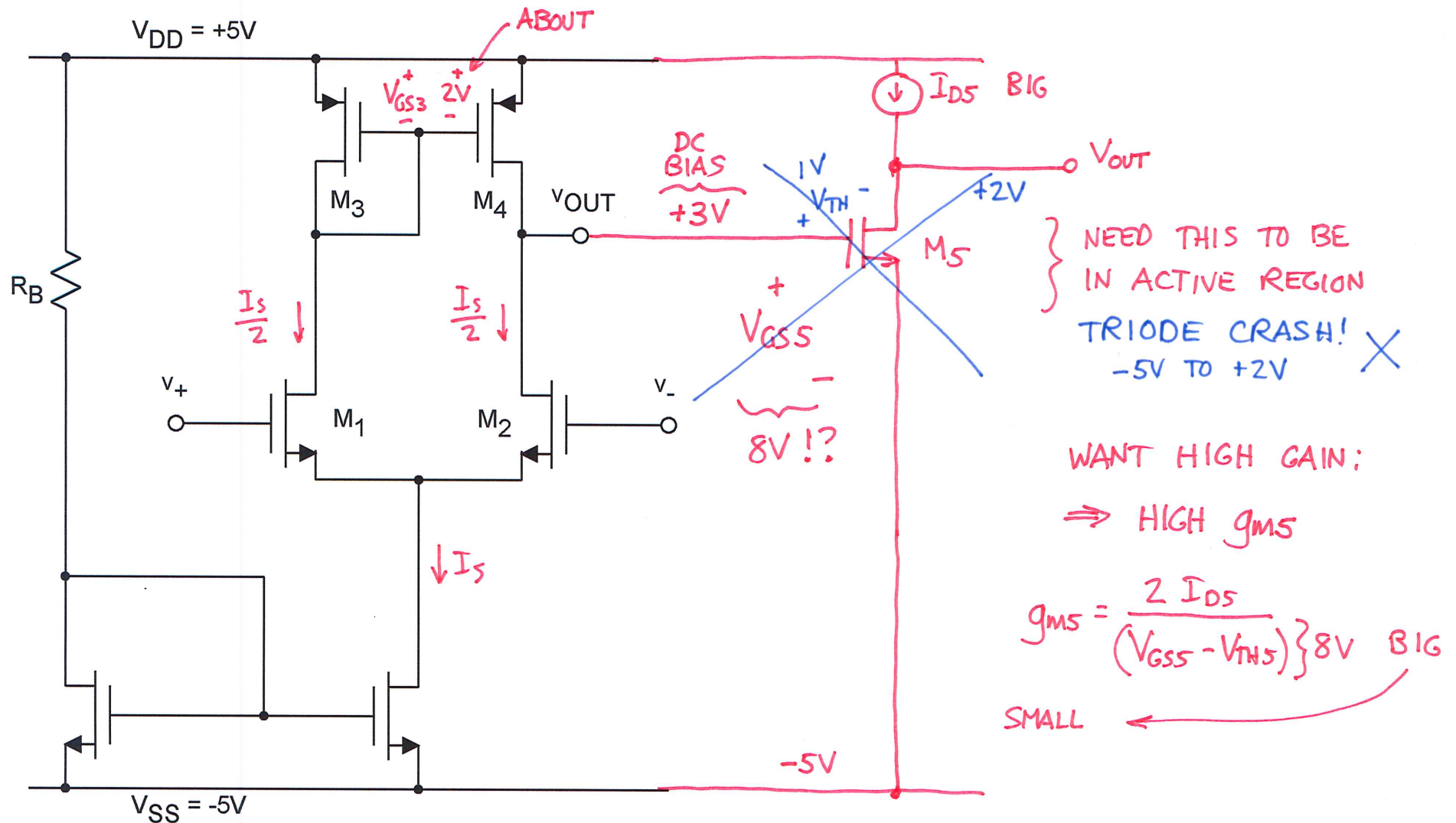
$$\frac{V_{out}}{V_{id}} = \frac{g_m R_{out}}{1 + s R_{out} C_L}$$

$$f_{3dB} = \frac{1}{2\pi R_{out} C_L}$$

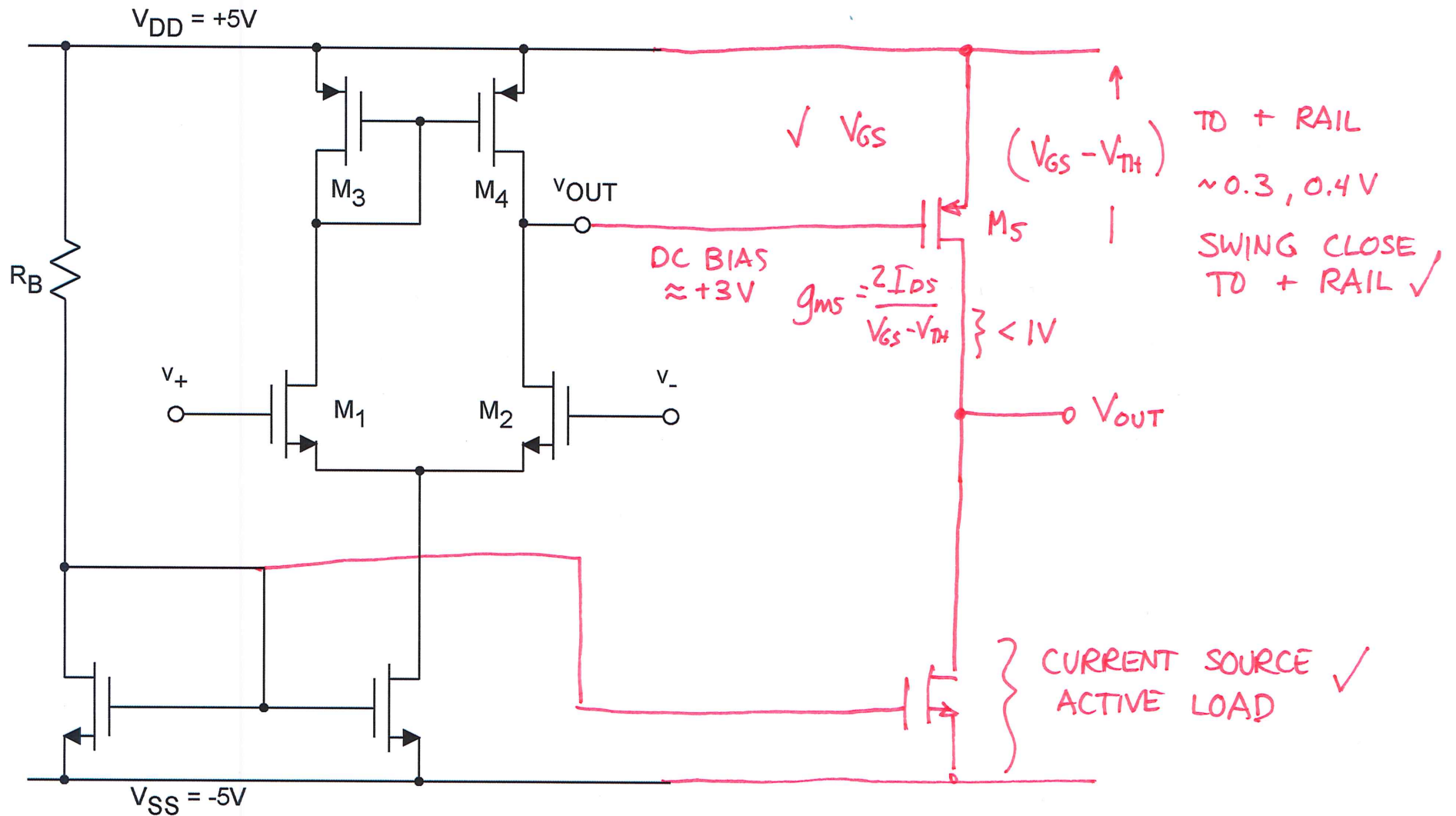


2nd Stage Common Source Amplifier: NMOS or PMOS?

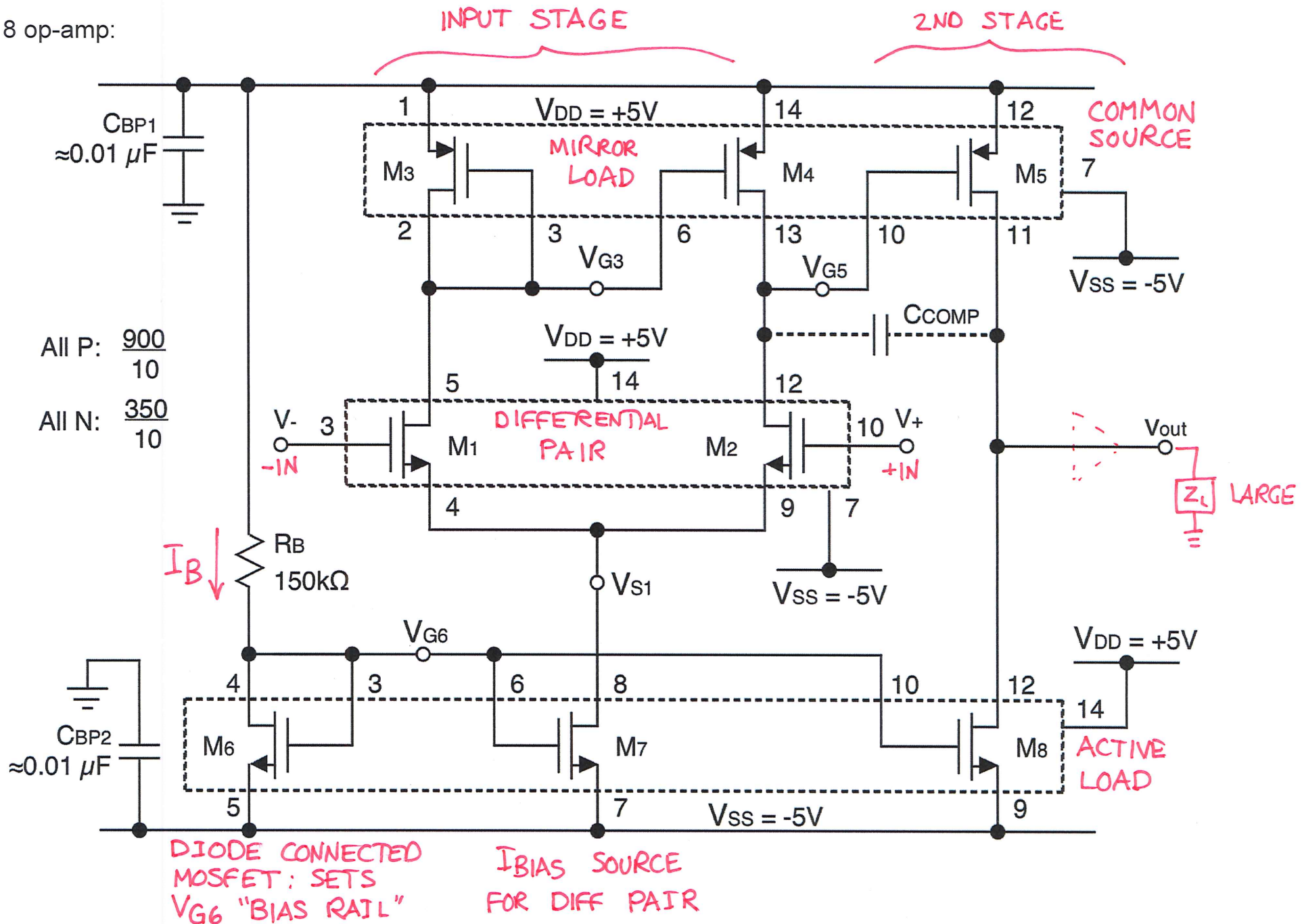
COMMON SOURCE WITH ACTIVE LOAD



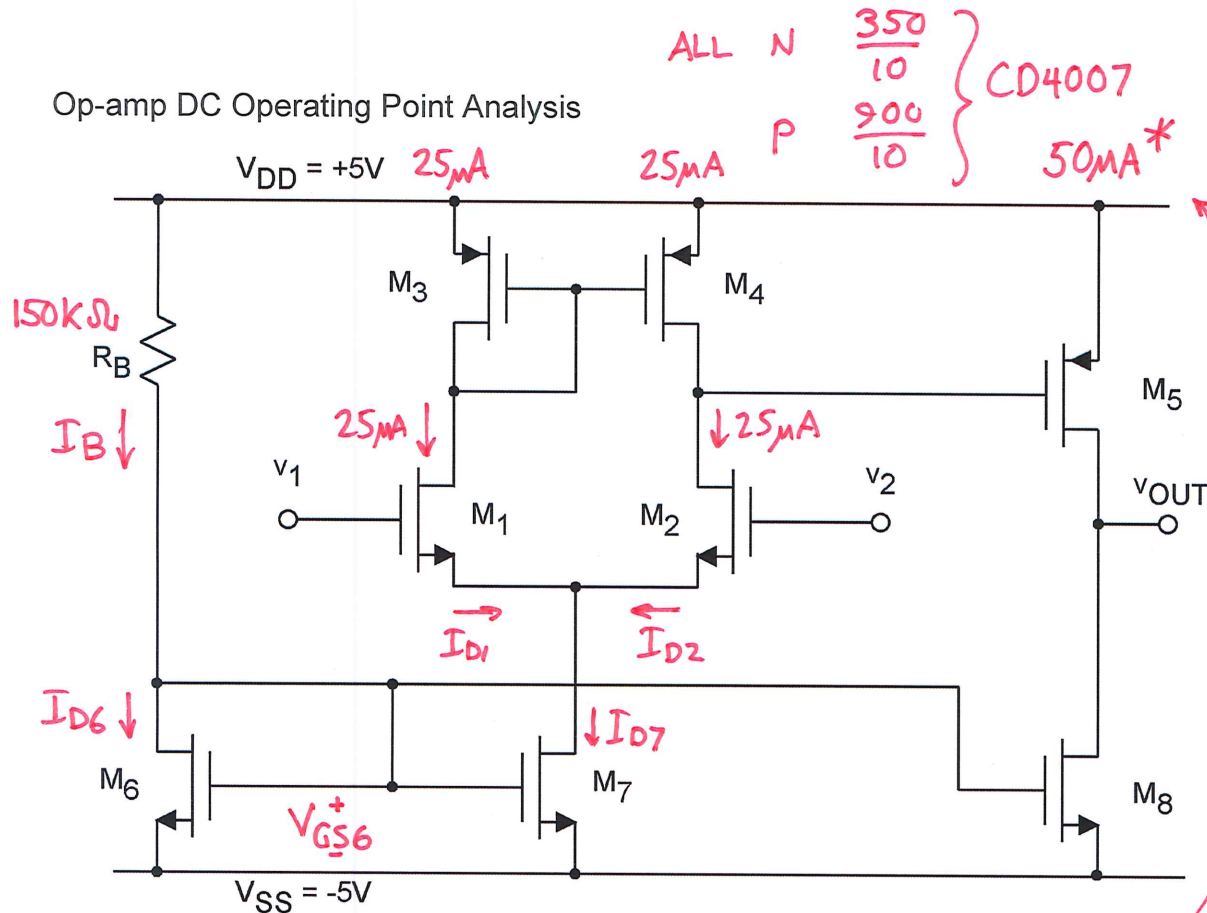
2nd Stage Common Source Amplifier: NMOS or PMOS? FOR COMMON SOURCE?



Lab 8 op-amp:



Op-amp DC Operating Point Analysis



Parameter	N-channel	P-channel	Units
V_{TH}	+1.90	-1.60	V
μC_{ox}	2.6E-5	9.1E-6	A/V ²
λ (L=10µm)	0.05	0.028	V ⁻¹

STRATEGY: FOLLOW CURRENT AROUND
START: I_B IN BIAS FOR MIRROR
OHM'S LAW FOR R_B :

$$+5V - I_B R_B - V_{GS6} = -5V$$

$$I_B = \frac{10V - V_{GS6}}{R_B} \quad \text{SQ LAW } I_{D6} = I_B$$

SOLVE QUADRATIC ☹

NEED $\pm 20\%$

GUESS FOR $V_{GS6} = 2.5V$?!

$$\text{TRY } \frac{10V - 2.5V}{150k\Omega} = 50\mu A$$

CHECK IN SQUARE LAW:

$$50\mu A = \frac{2.6E-5}{2} \frac{350}{10} (V_{GS6} - 1.9V)^2$$

$$\Rightarrow V_{GS6} = 2.23V$$

REVISE I_B

$$\frac{10V - 2.23V}{150k\Omega} = 51\mu A$$

$$I_{D1} + I_{D2} = I_{D7} = 50\mu A$$

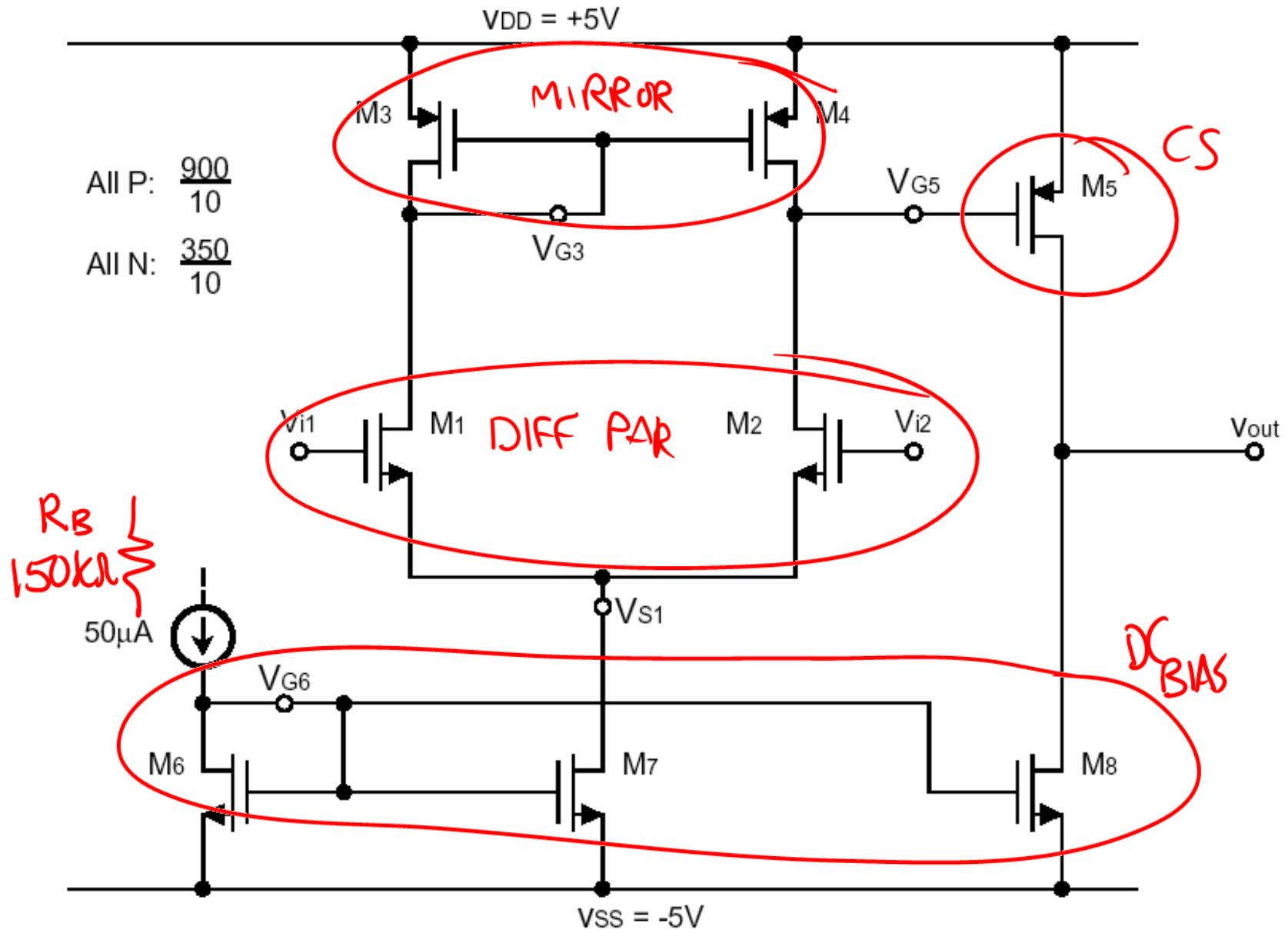
EQUAL

V_{GS} VALUES FROM SQ LAW

Labs 8 & 9 Review

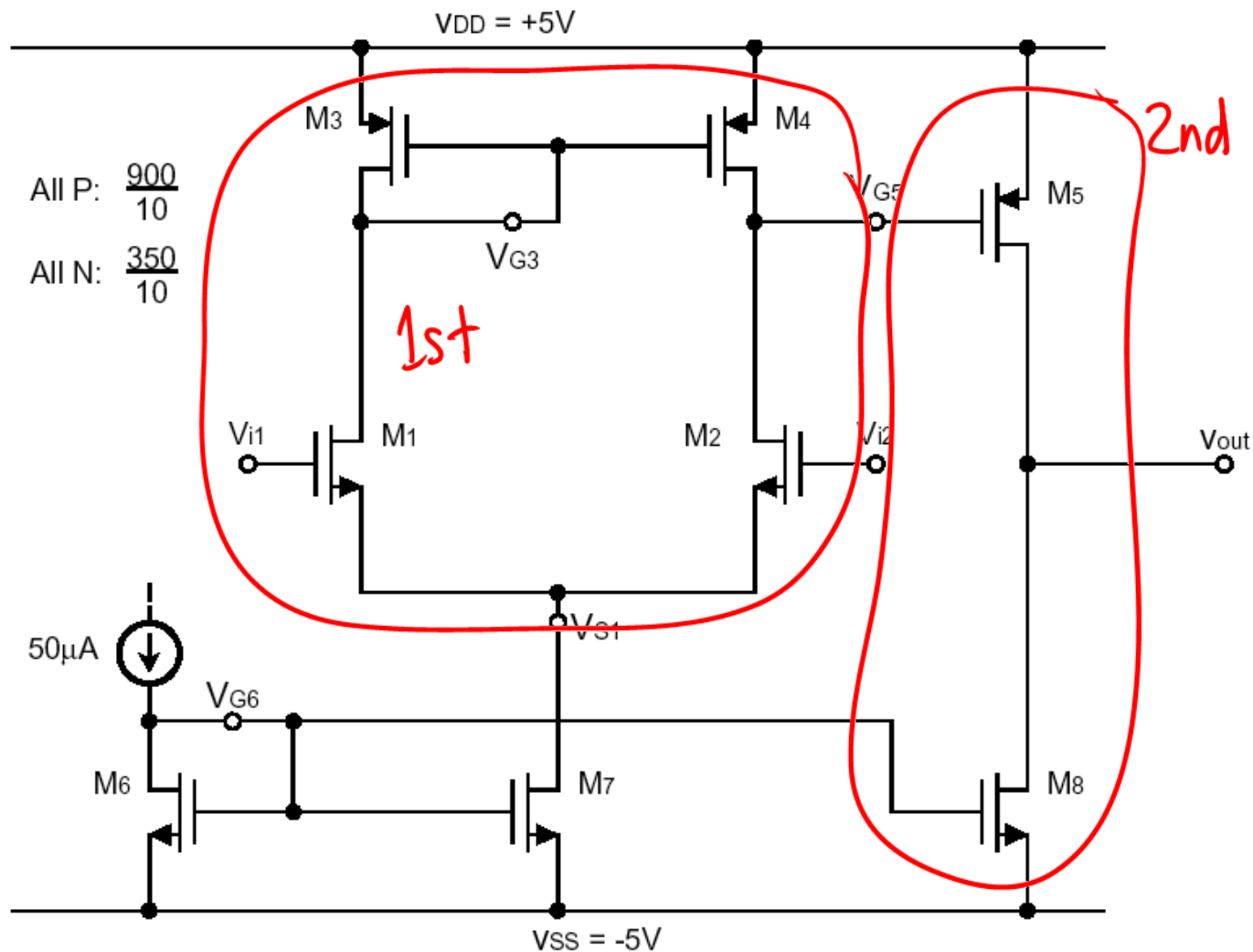
- **Operational Amplifier**
 - **Stability**
 - **Compensation**
 - **Miller Effect**
 - **Phase Margin**
 - **Unity Gain Frequency**
 - **Slew Rate Limiting**
- **Reading: Razavi ch. 9, 10**
 - **Lab 8, 9 op-amp is Fig. 10.34 in sec. 10.5.1**
 - **(see also Johns & Martin sec 5.2 pp. 232-242)**

Two-stage op-amp

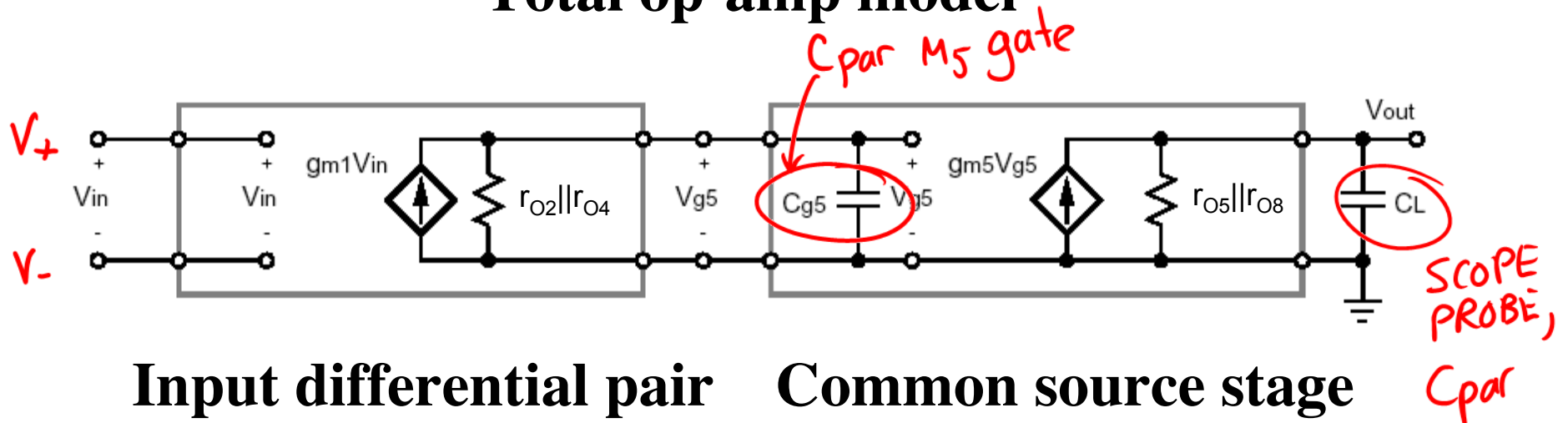


Analysis Strategy

- Recognize sub-blocks
- Represent as cascade of simple stages



Total op-amp model



$$g_{m1} = \frac{2I_{D1}}{(V_{GS1} - V_{TH1})}$$

$$\frac{r_{o2} || r_{o4}}{(\lambda_2 + \lambda_1) I_{D1}}$$

$$g_{m2} = \frac{2I_{D5}}{(V_{G5} - V_{TH5})}$$

$$\frac{r_{o5} || r_{o8}}{(\lambda_5 + \lambda_8) I_{D5}}$$

DC operating point

	$I_D[\mu A]$	$V_{GS}-V_{TH}$
M1	25	0.235
M2	25	0.235
M3	25	0.247
M4	25	0.247
M5	50	0.350
M6	50	0.332
M7	50	0.332
M8	50	0.332

I_D
ANALYSIS

SQ
LAW

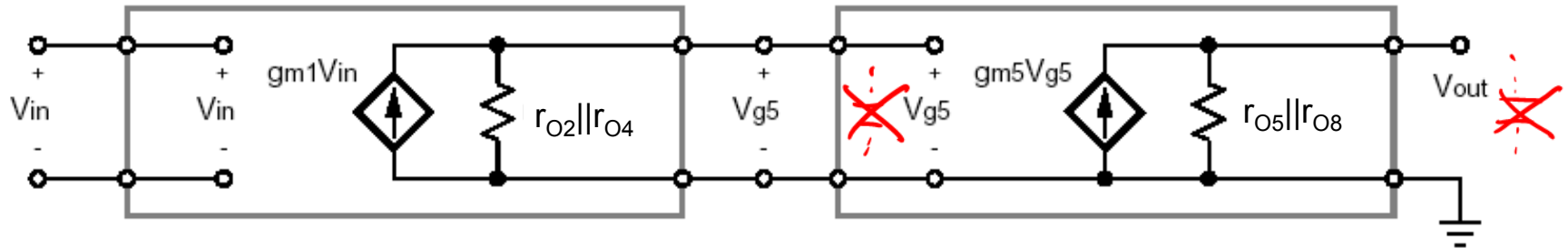
Small signal parameters

	$I_D[\mu A]$	$V_{GS}-V_{TH}$	$g_m[\mu A/V]$	r_o	
M1	25	0.235	208		} 1st
M2	25	0.235		800kΩ	
M3	25	0.247			
M4	25	0.247		1.43MΩ	
M5	50	0.350	285	715kΩ	} 2nd
M6	50	0.332			
M7	50	0.332			
M8	50	0.332		400kΩ	

Note: $\lambda_n = 0.050 \text{ V}^{-1}$; $\lambda_p = 0.028 \text{ V}^{-1}$

Total op-amp model: Low frequency gain

CAP OPEN



Input differential pair

$$a_{v1} = g_{m1}(r_{O2}||r_{O4})$$

$$a_{v1} = (208\mu A/V)(800k\Omega||1.43M\Omega)$$

$$a_{v1} = 106$$

Common source stage

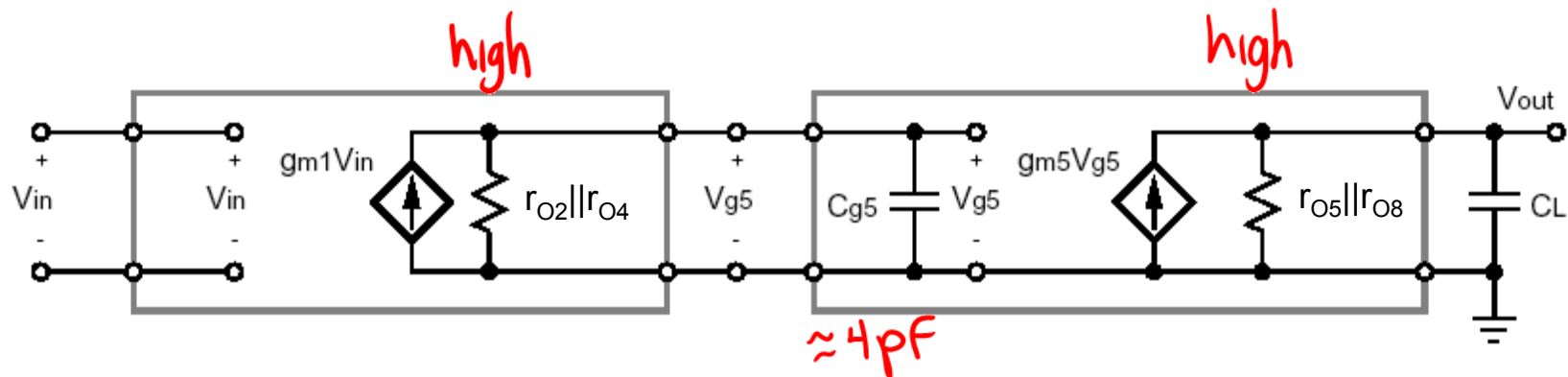
$$a_{v2} = g_{m2}(r_{O5}||r_{O8})$$

$$a_{v2} = (285\mu A/V)(400k\Omega||715k\Omega)$$

$$a_{v2} = 73$$

$$\frac{V_{out}}{V_{in}} \sim 7000$$

Total op-amp model with capacitances



Gate of M5

Load: scope probe $\approx 10\text{pF}$

$$C_g = (900\mu\text{m})(10\mu\text{m})\left(4.17E-4\frac{\text{F}}{\text{m}^2}\right)$$

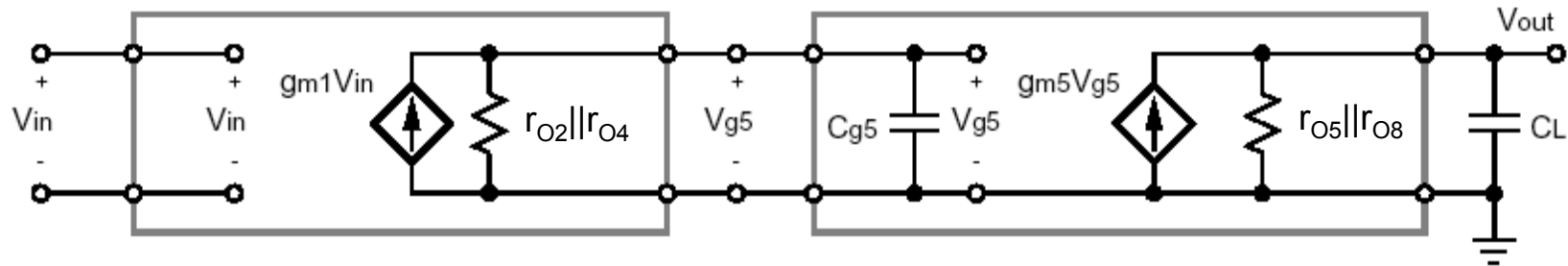
$$C_g = 3.74\text{pF}$$



EACH CAP: 1 POLE TO TRANSFER FUNCTION $\frac{V_{out}(f)}{V_{in}}$

ONLY 2 HIGH IMPEDANCE NODES: V_{g5} , V_{out}
 DOMINANT POLE

Total op-amp model with capacitances



First stage pole

$$f_{p1} = \frac{1}{2\pi(r_{O2} || r_{O4})C_{g5}}$$

$$f_{p1} = \frac{1}{2\pi(800k\Omega || 1.43M\Omega)(3.74pF)}$$

$$f_{p1} = \underline{82kHz}$$

Second stage pole

$$f_{p1} = \frac{1}{2\pi(r_{O5} || r_{O8})C_L}$$

$$f_{p1} = \frac{1}{2\pi(400k\Omega || 715k\Omega)(10pF)}$$

$$f_{p1} = \underline{61kHz}$$

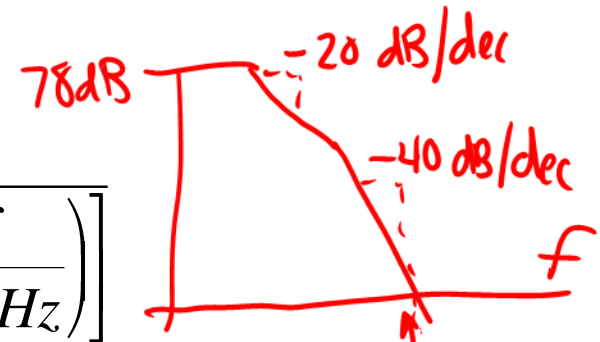
Open loop transfer function

- Product of individual stage transfer functions

$$A(j\omega) = \frac{\overbrace{g_{m1}(r_{O2} \parallel r_{O4})}^{106} \overbrace{g_{m5}(r_{O5} \parallel r_{O8})}^{73}}{\underbrace{\left[1 + j\omega(r_{O2} \parallel r_{O4})C_{gs}\right]}_{1st} \underbrace{\left[1 + j\omega(r_{O5} \parallel r_{O8})C_L\right]}_{2nd}}$$

- Numerically (using $\omega = 2\pi f$)

$$A(j\omega) = \frac{7738}{\left[1 + j\left(\frac{f}{82kHz}\right)\right] \left[1 + j\left(\frac{f}{61kHz}\right)\right]}$$



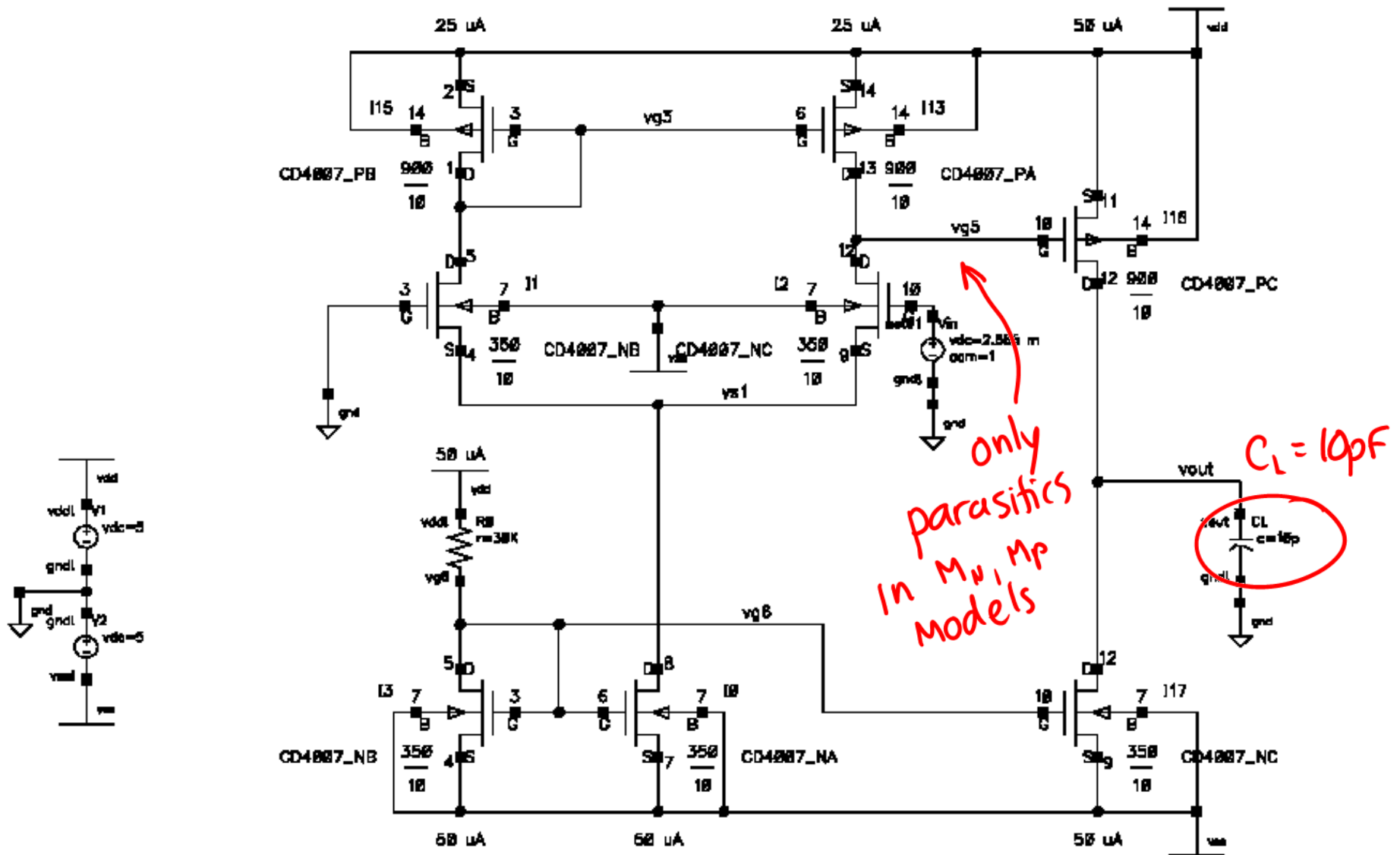
- Check Bode plot simulation; predicts:

– DC gain = $20\log(7738) = +78\text{dB}$

– Unity gain frequency $\sim 6.2\text{ MHz}$

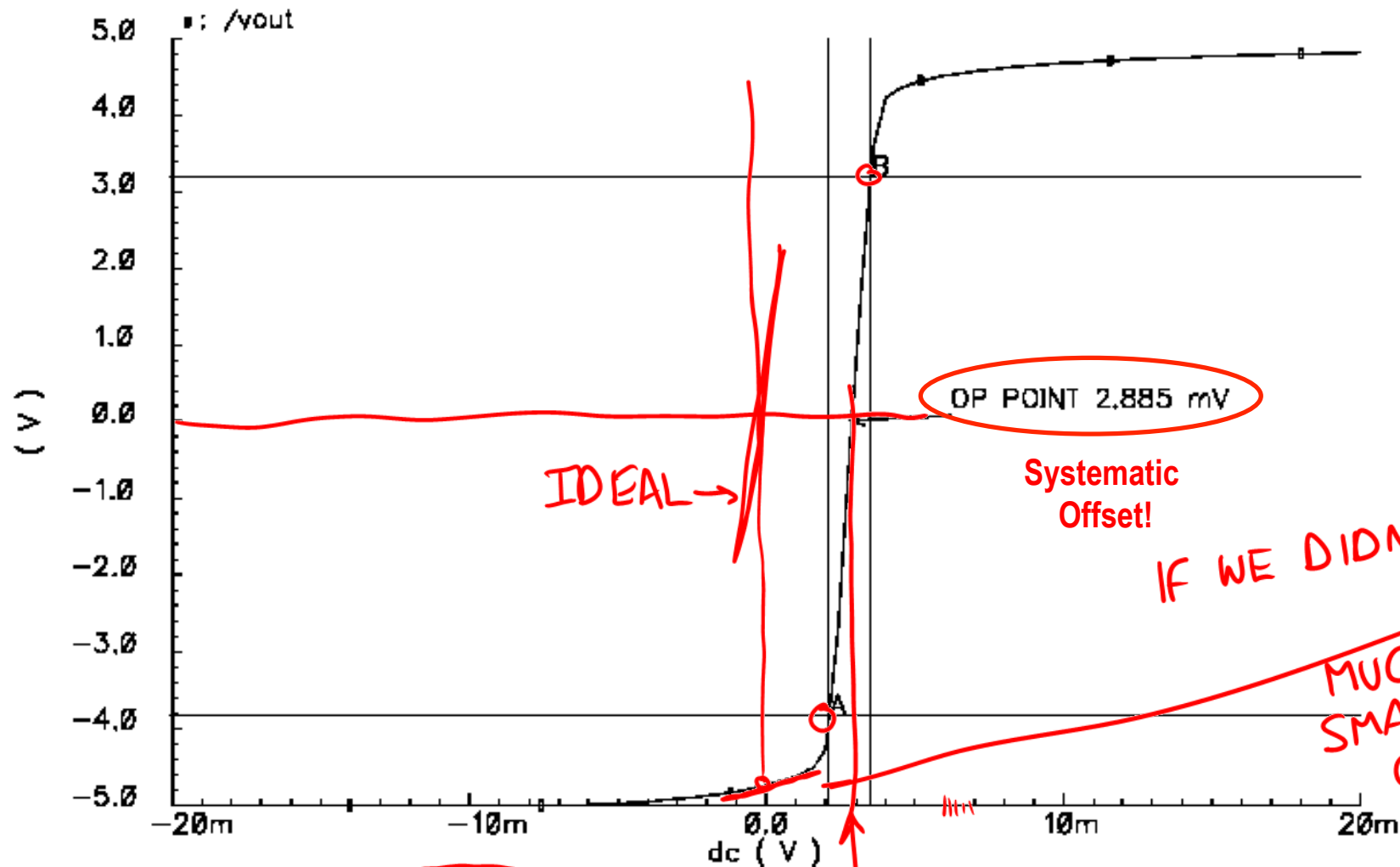
(SET $|A(\omega)| = 1$)

Two-stage op-amp: Simulation Schematic



DC Operating Point Simulation

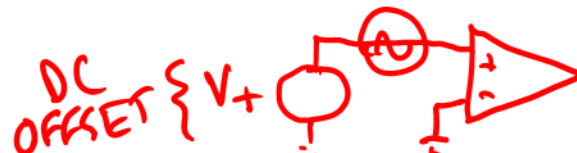
DC Response



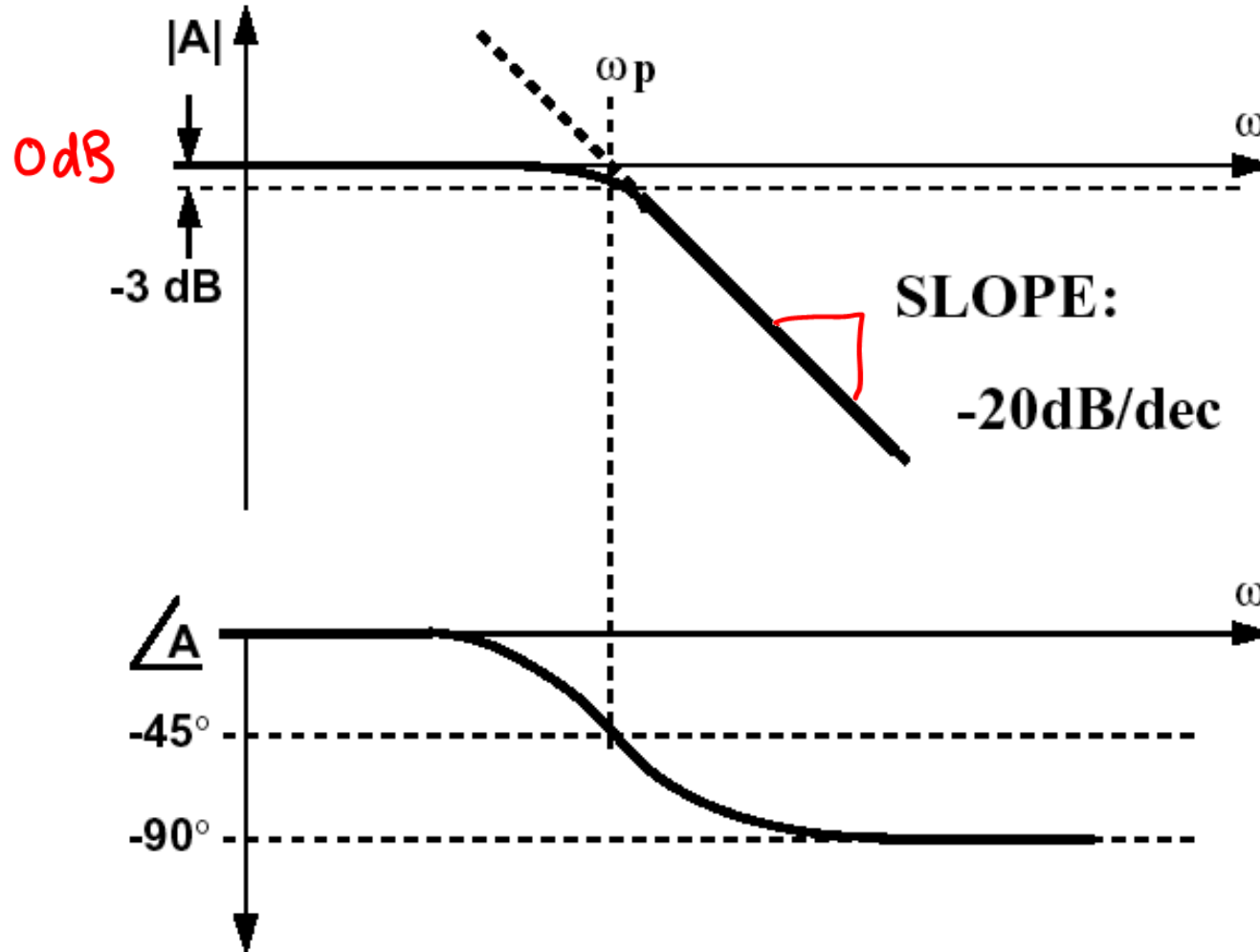
A: {2.11783m -3.81929} delld: {1.39772m 7.02858}
B: {3.51555m 3.20929} slope: 5.02681K

7700 $\neq$ ~5000

A_L LARGE



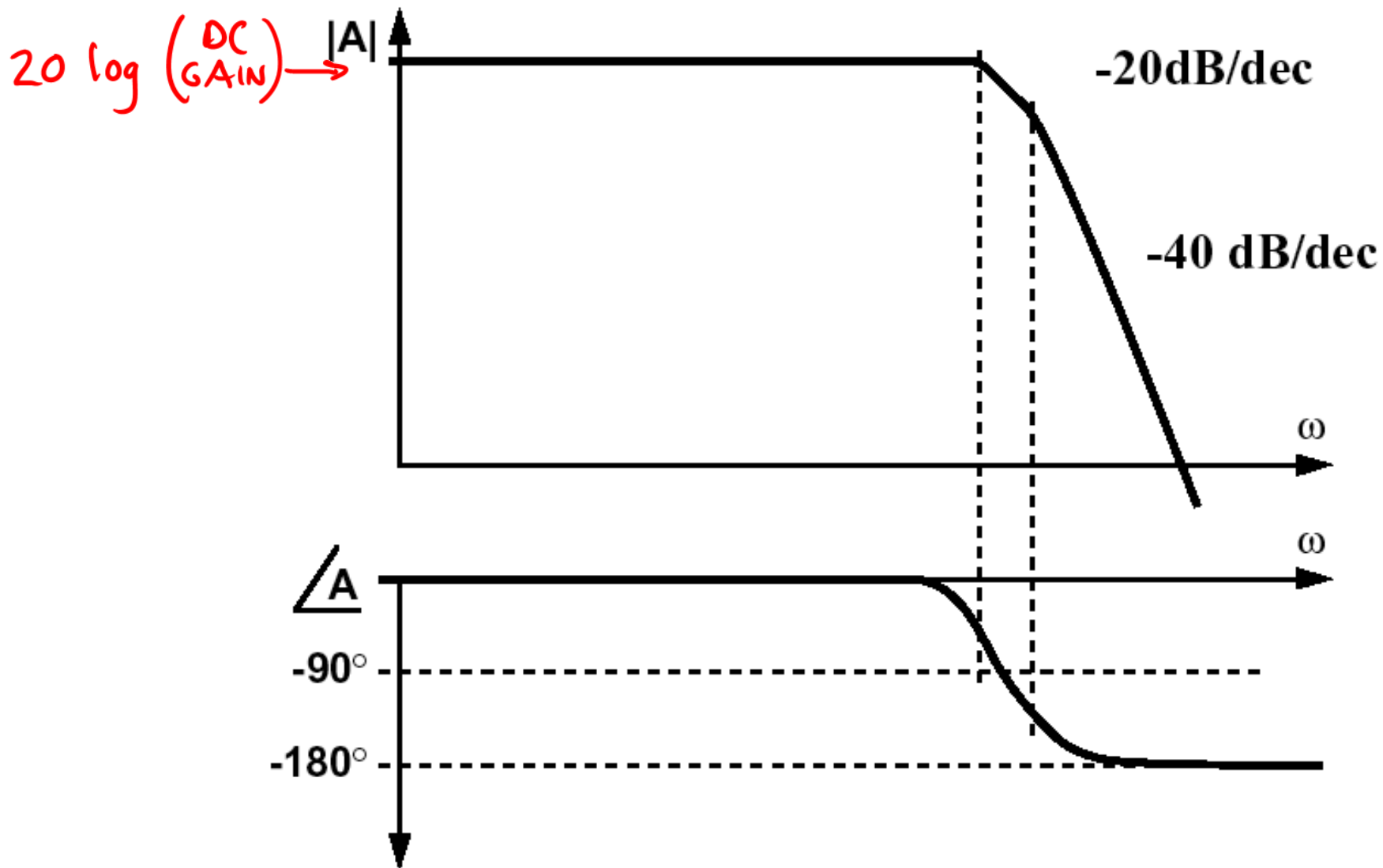
Bode plot EACH POLE TERM



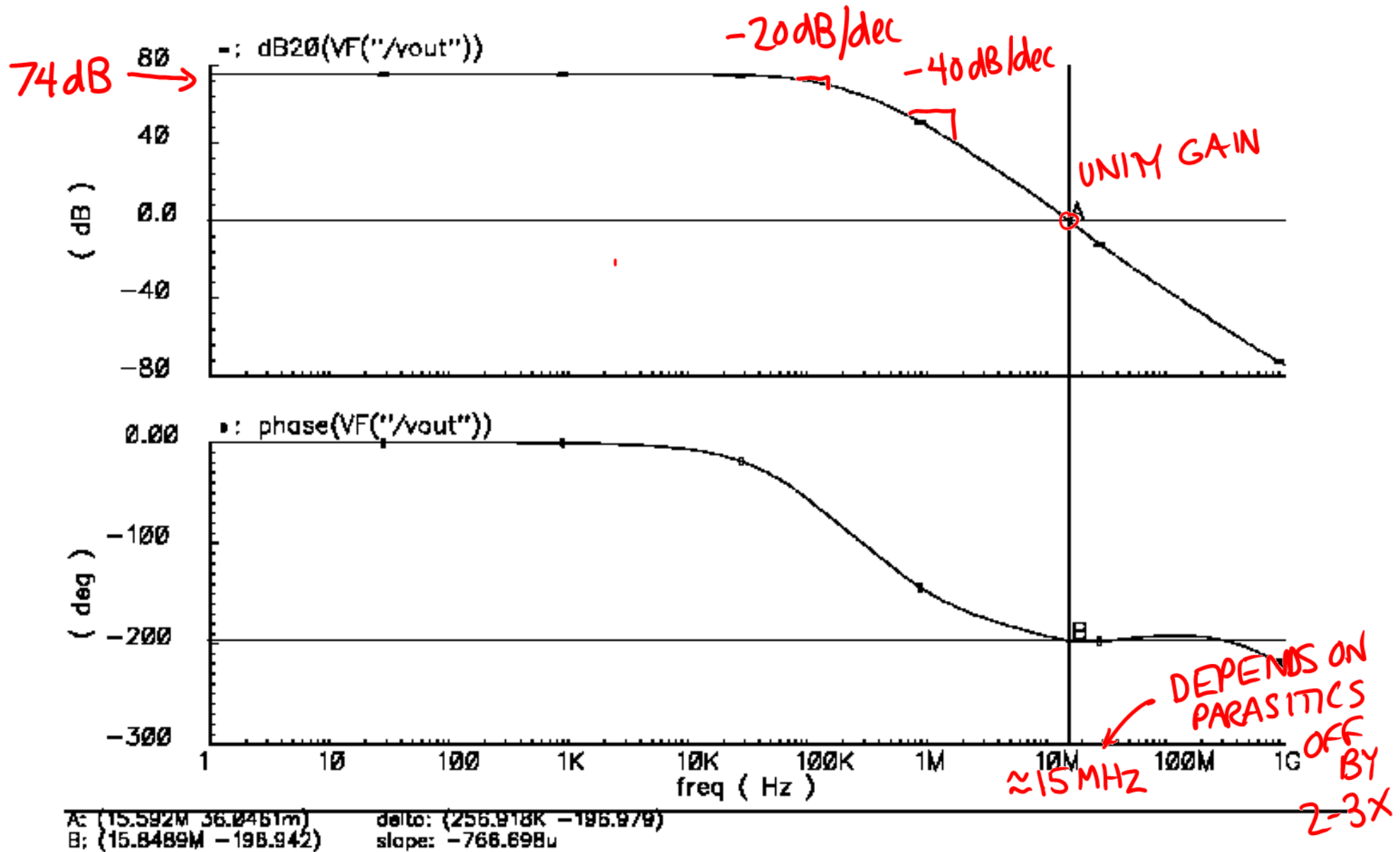
- Magnitude, phase on log scales
- Pole: Root of denominator polynomial

Open loop Bode plot

- Product of terms : Sum on log-log plot

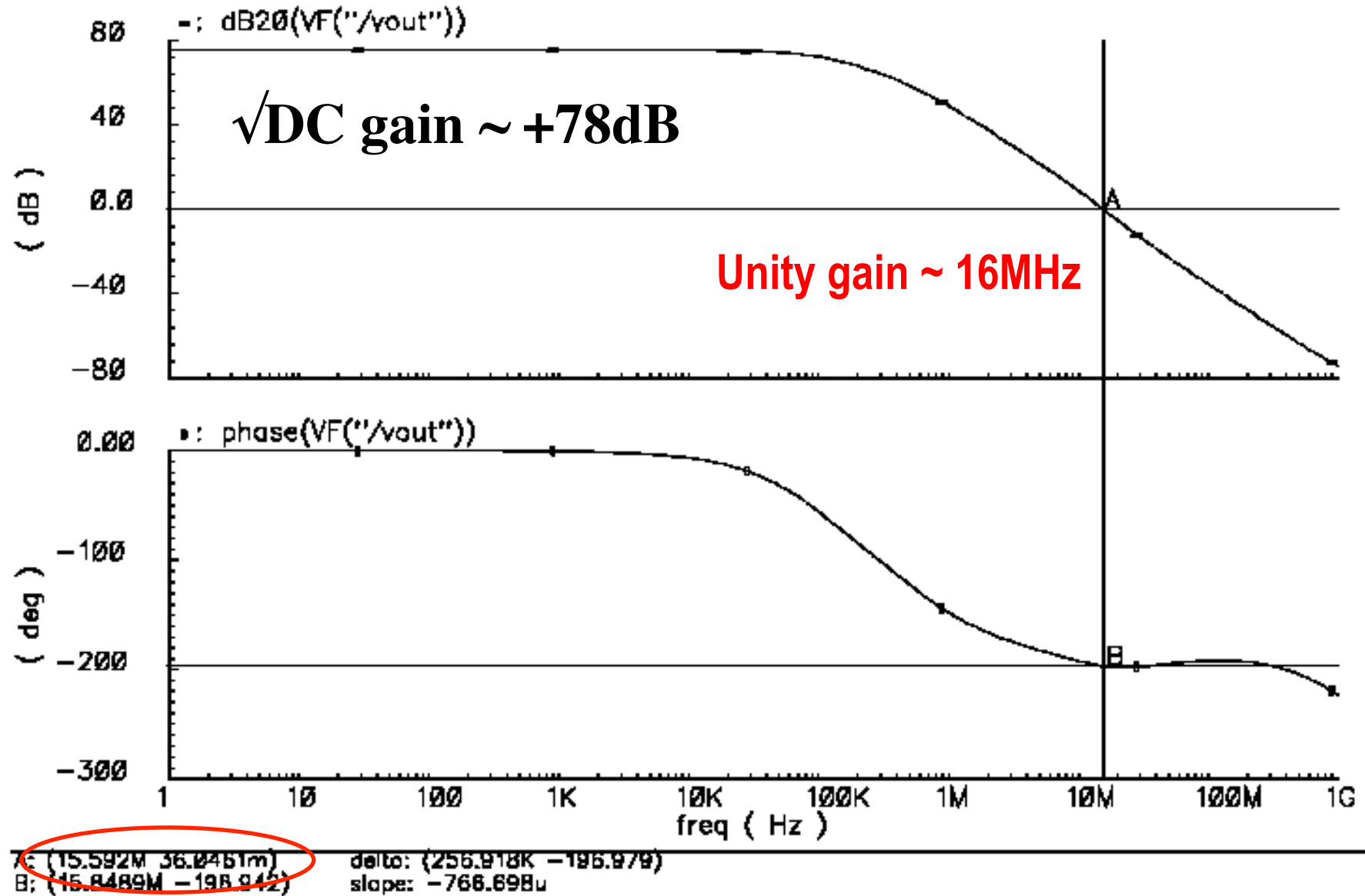


Open Loop Bode Plot Simulation

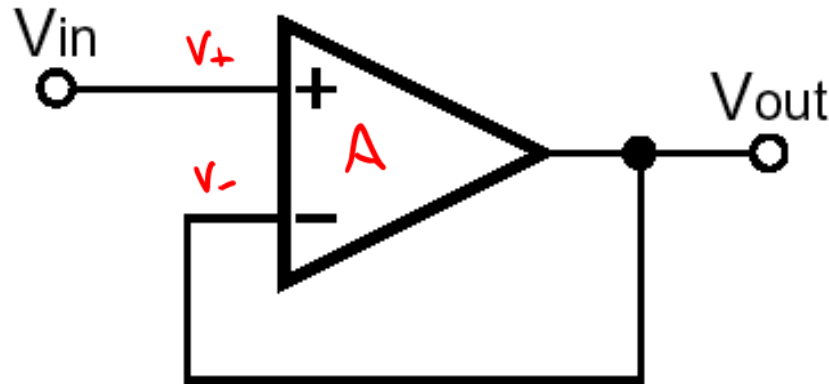


Note: AC source at input also needs DC component to account for systematic offset!

Check Open Loop Bode Plot Simulation



Stability example: Closed loop follower



- **Negative feedback:**
Output connected to inverting input
- **Gain should be ~ 1**

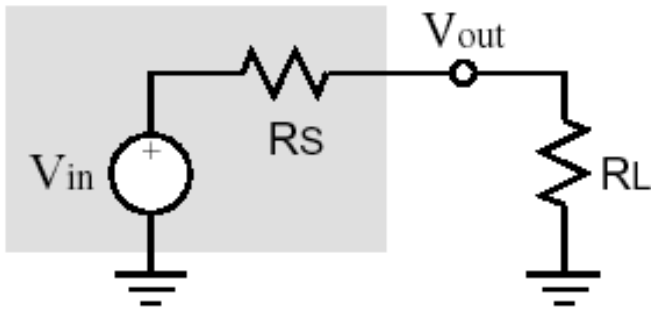
$$v_{out} = A(v_{in} - v_{out})$$

$$v_{out}(A + 1) = Av_{in}$$

$$v_{out} = \underbrace{\left(\frac{A}{A + 1} \right)}_{\approx 1 \text{ as } A \gg 1} v_{in}$$

Unity gain: Why bother?

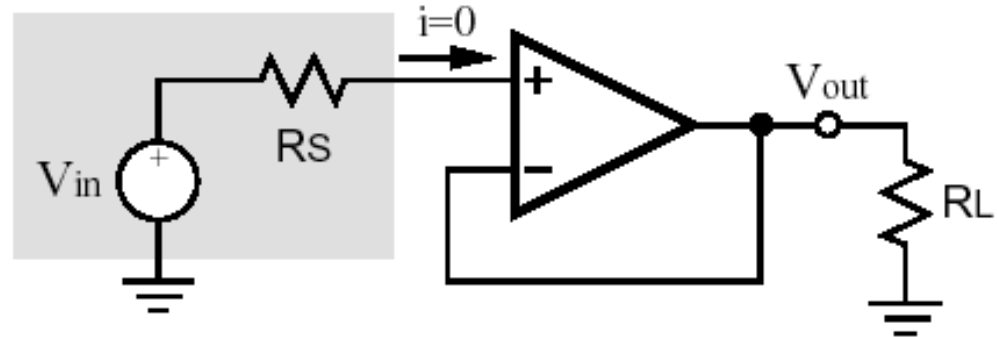
SOURCE MODEL



$$v_{out} = \left(\frac{R_L}{R_L + R_S} \right) v_{in}$$

- **No buffer:**
Voltage divider
- **Signal reduced due to voltage drop across R_S**

SOURCE MODEL

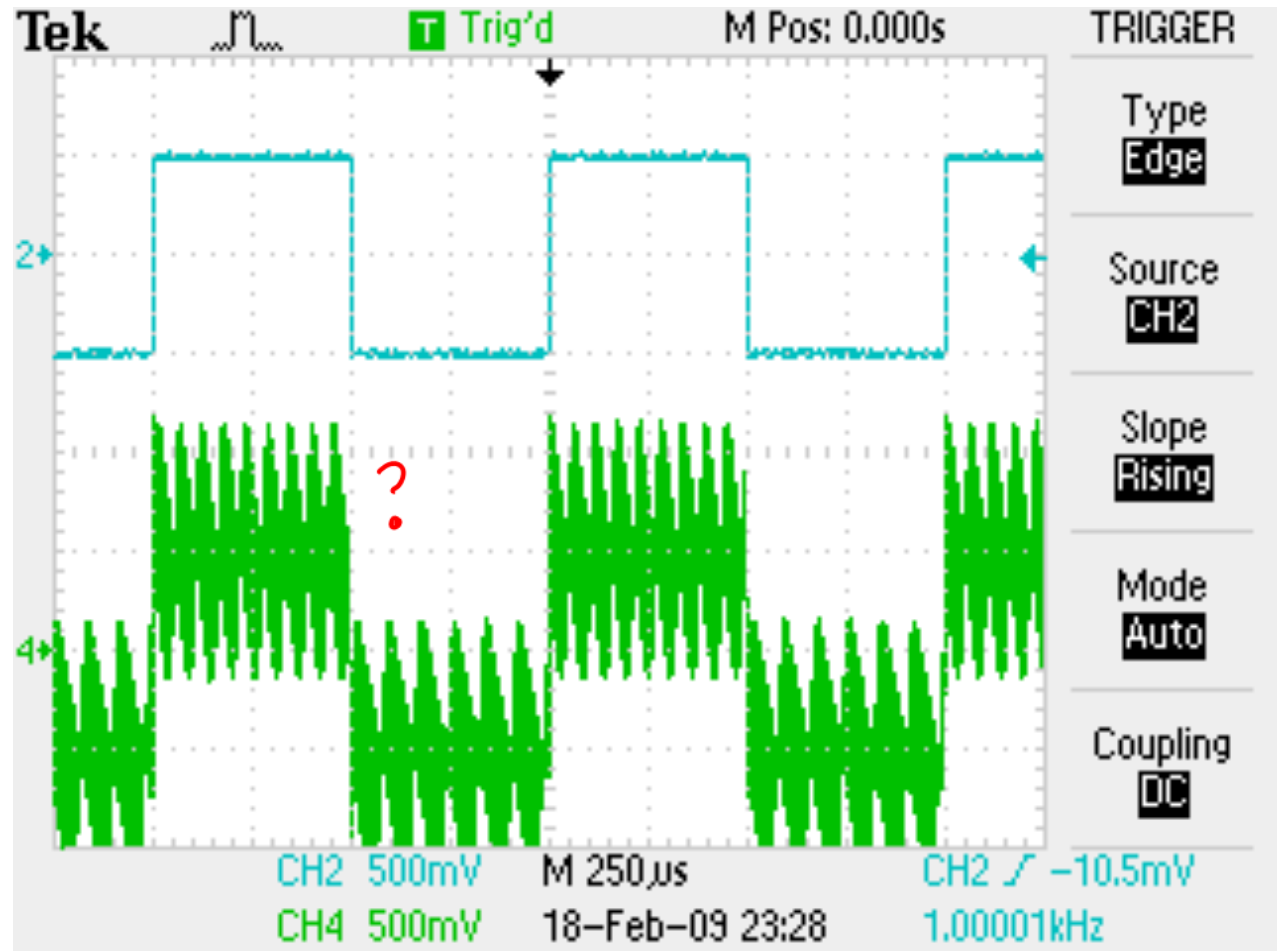
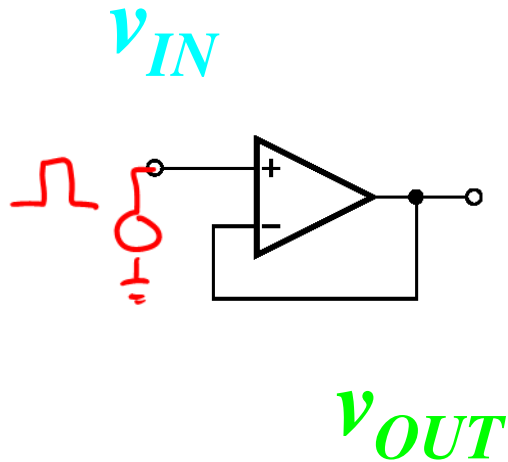


$$v_{out} = v_{in}$$

- **With buffer:**
No current required from source

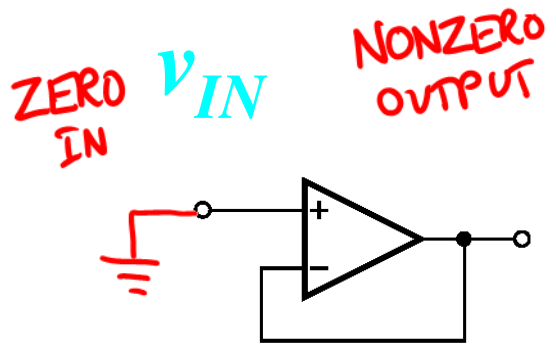
Lab 9 Problem: Instability

- Oscillation superimposed on desired output!?!



Lab 9 Problem: Instability

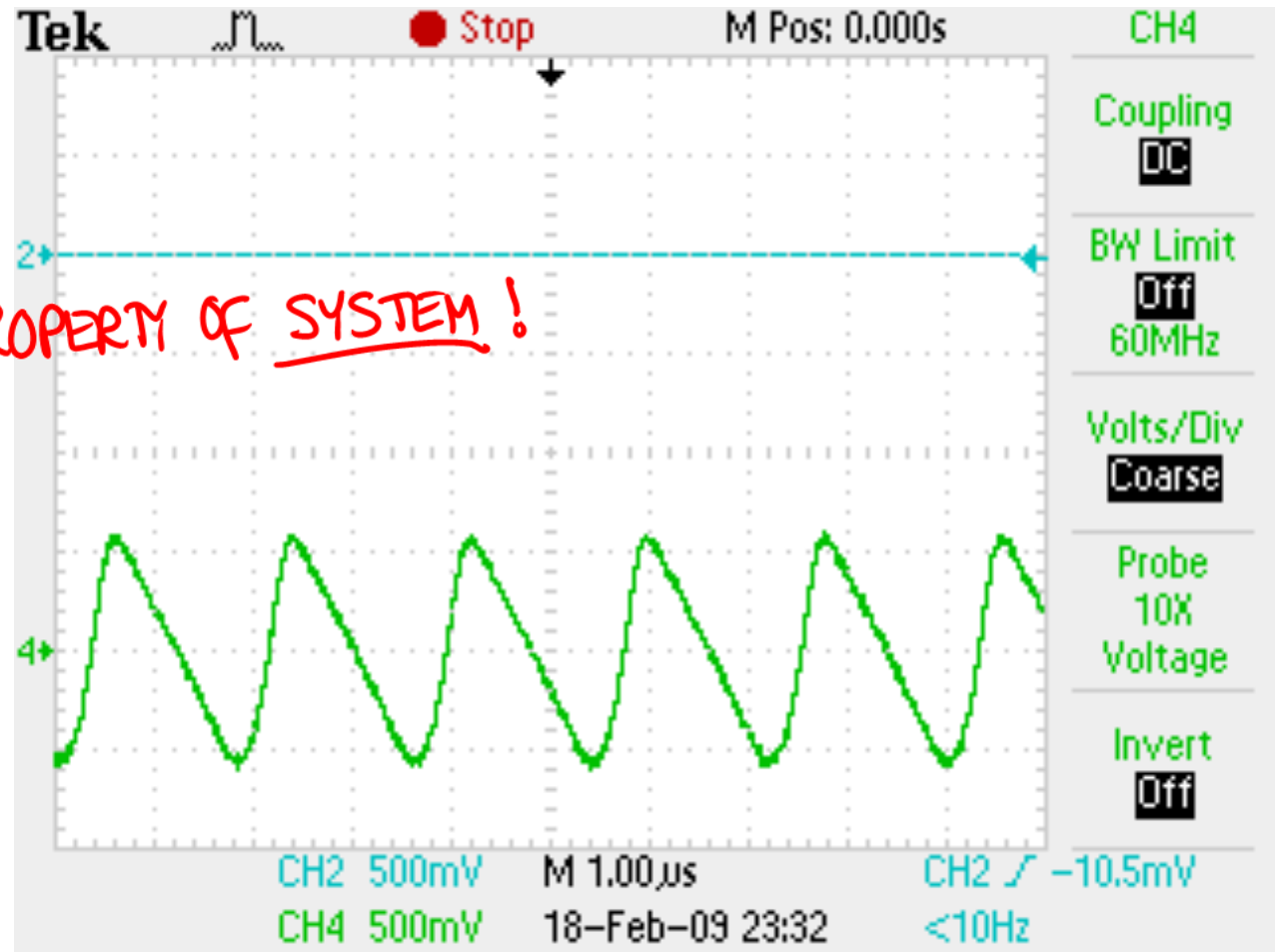
- Ground v_{in} : Output for zero input?!?
- Why? Need...



FOR THIS WAVEFORM

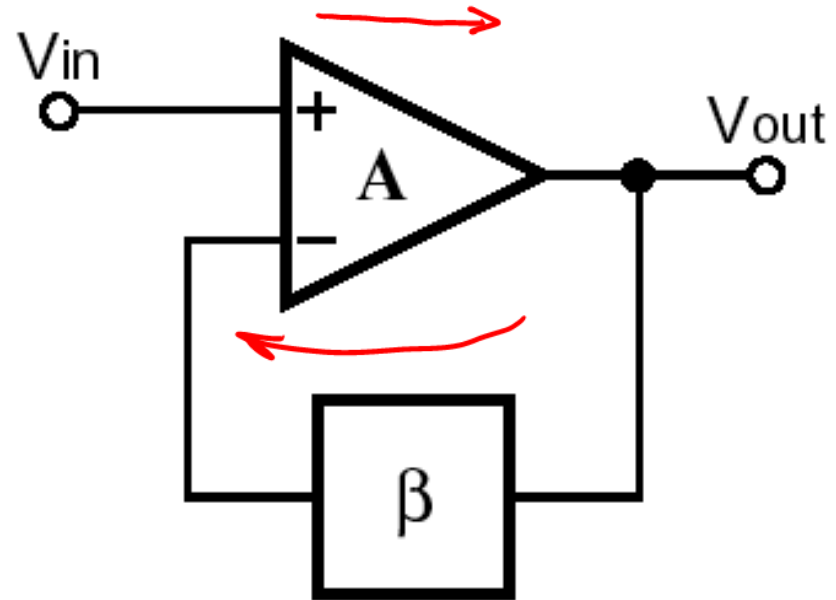
$$\frac{V_{out}}{V_{in}} = \infty$$

PROPERTY OF SYSTEM!



Controls: ECE3012 in 20 minutes

- **General framework**
A: Forward Gain
 β : Feedback Factor
fraction of output
fed back to input



Example: Op-amp, Noninverting Gain

A: Forward Gain

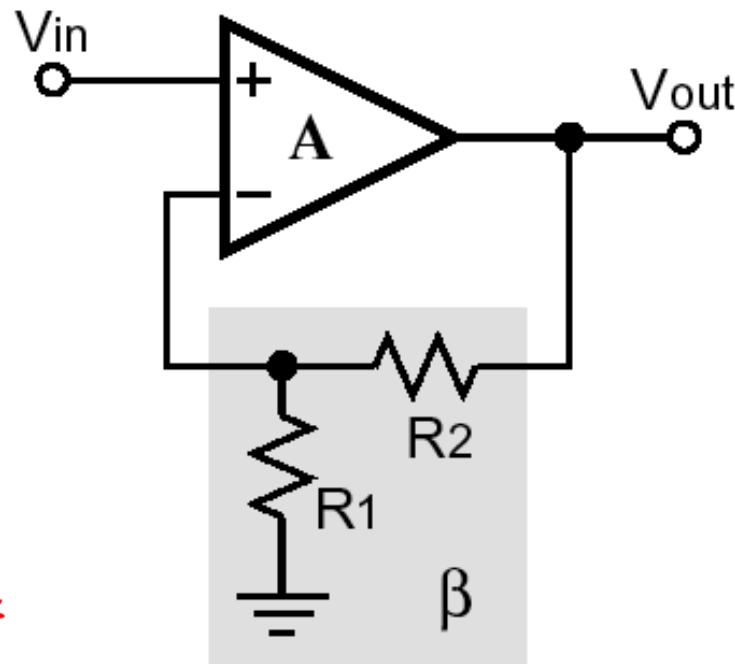
Op-amp open loop gain

$$V_{\text{out}} = A(V_{+} - V_{-})$$

Transfer function $A(j\omega)$

β : Feedback Factor

$$\beta = \frac{R_1}{R_1 + R_2} \quad \text{VOLTAGE DIVIDER}$$



Closed Loop Gain

- **Output**

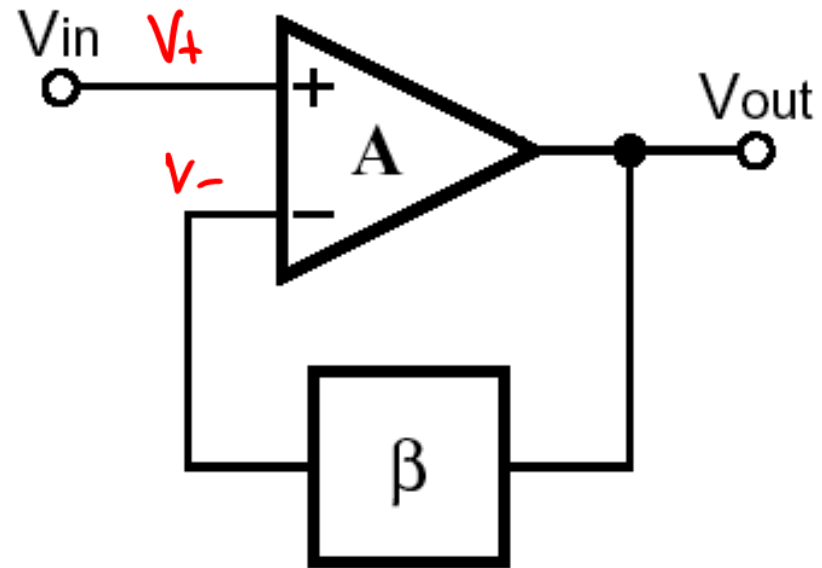
$$v_{out} = A \underbrace{(v_{in} - \beta v_{out})}_{v_+ - v_-}$$

- **Solve for v_{out}/v_{in}**

$$v_{out} = Av_{in} - A\beta v_{out}$$

$$(1 + A\beta)v_{out} = Av_{in}$$

$$\boxed{\frac{v_{out}}{v_{in}} = \frac{A}{1 + A\beta}}$$



Op-amp with negative feedback

- If $A\beta \gg 1$

$$\frac{v_{out}}{v_{in}} = \frac{A}{1 + A\beta} \approx \frac{A}{A\beta} \rightarrow \frac{v_{out}}{v_{in}} \approx \frac{1}{\beta}$$

- Closed loop gain determined only by β
- Advantage of negative feedback:
Open loop gain A can be ugly (nonlinear, poorly controlled) as long as it's large!

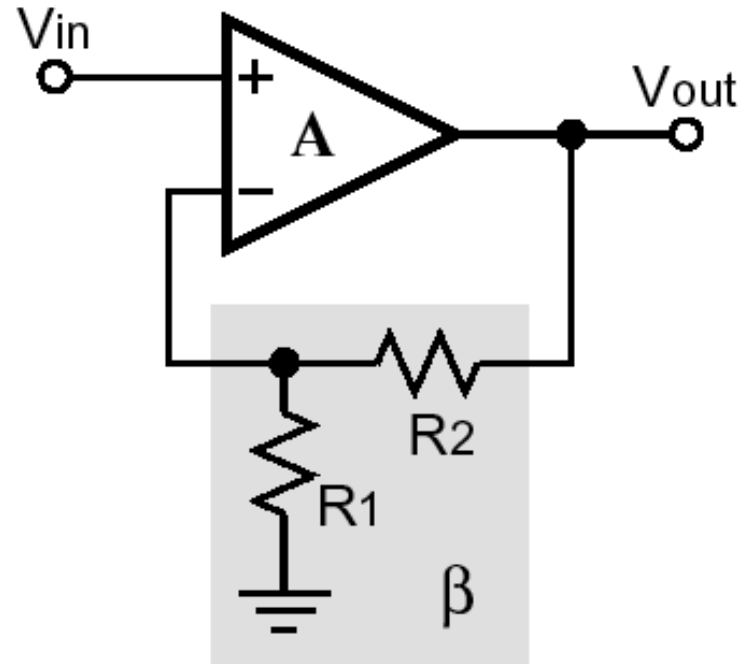
Example: Op-amp, Noninverting Gain

β : Feedback Factor

$$\beta = \frac{R_1}{R_1 + R_2}$$

Closed loop gain

$$\frac{v_{out}}{v_{in}} = \frac{R_1 + R_2}{R_1} = \frac{1}{\beta}$$



Reexamine closed loop transfer function

- **Output with no input:
infinite gain**

$$\infty \quad \frac{v_{out}}{v_{in}} = \frac{A}{1 + A\beta} \quad \} 0$$

- **Infinite when $1+A\beta = 0$**
- **Condition for oscillation:**

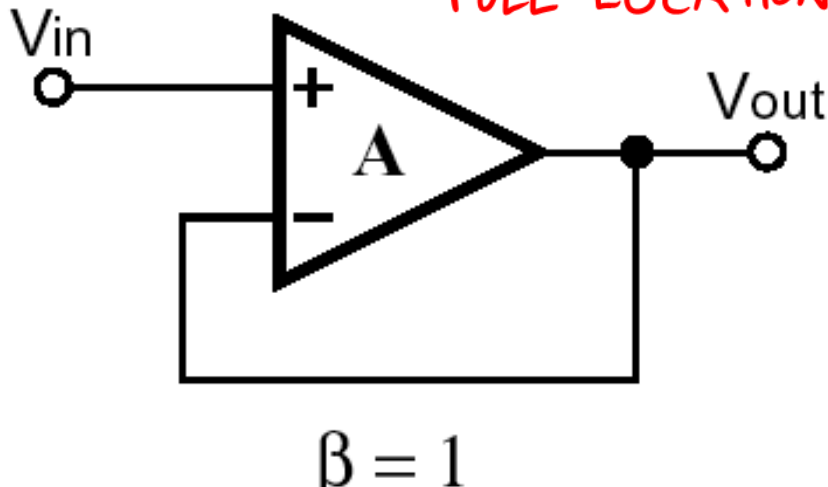
$$1+A\beta = 0$$

- **In general A, β functions of ω**
- **If there's a frequency ω at which $1+A\beta = 0$:
Oscillation at that frequency!**

Example: follower

$$\beta = 1 \rightarrow \frac{v_{out}}{v_{in}} = \frac{A}{1 + A}$$

TOO HARD TO FIND EXACT POLE LOCATIONS!



- Use $A(j\omega)$,
solve for $1 + A = 0$
- No thanks!

$$A(j\omega) = \frac{g_{m1}(r_{O2} \parallel r_{O4})g_{m5}(r_{O5} \parallel r_{O8})}{\left[1 + j\omega(r_{O2} \parallel r_{O4})C_{g5}\right]\left[1 + j\omega(r_{O5} \parallel r_{O8})C_L\right]}$$

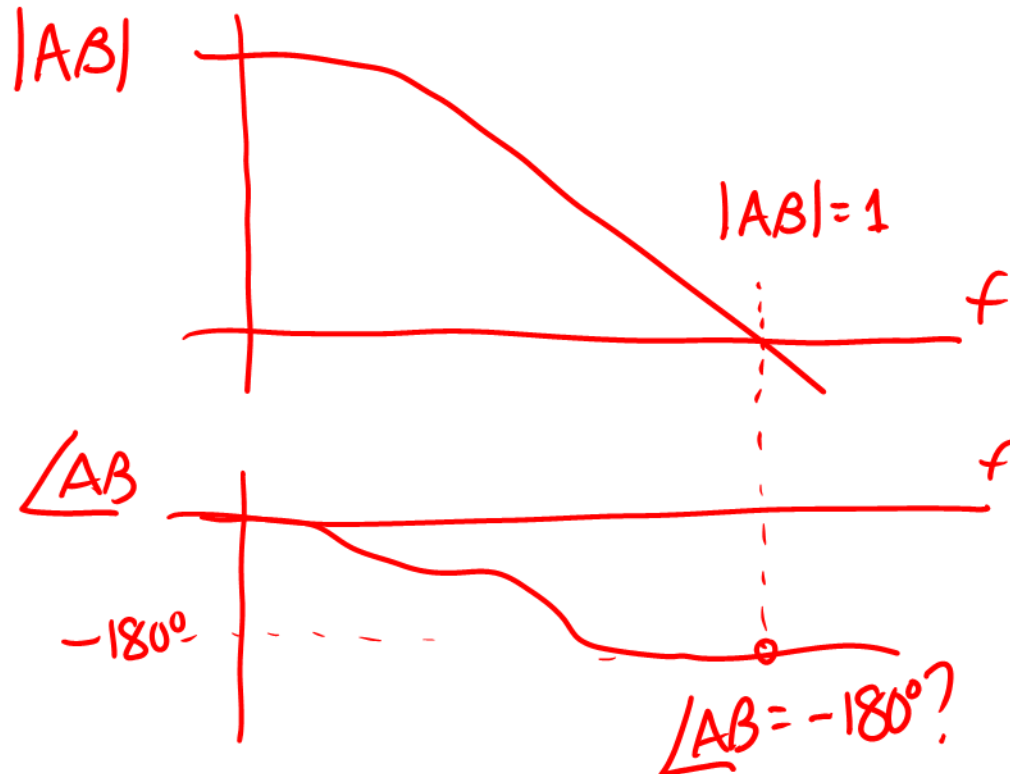
Reexamine condition for oscillation

DEN { $1 + A\beta = 0 \rightarrow A\beta = -1$

Magnitude and phase condition:

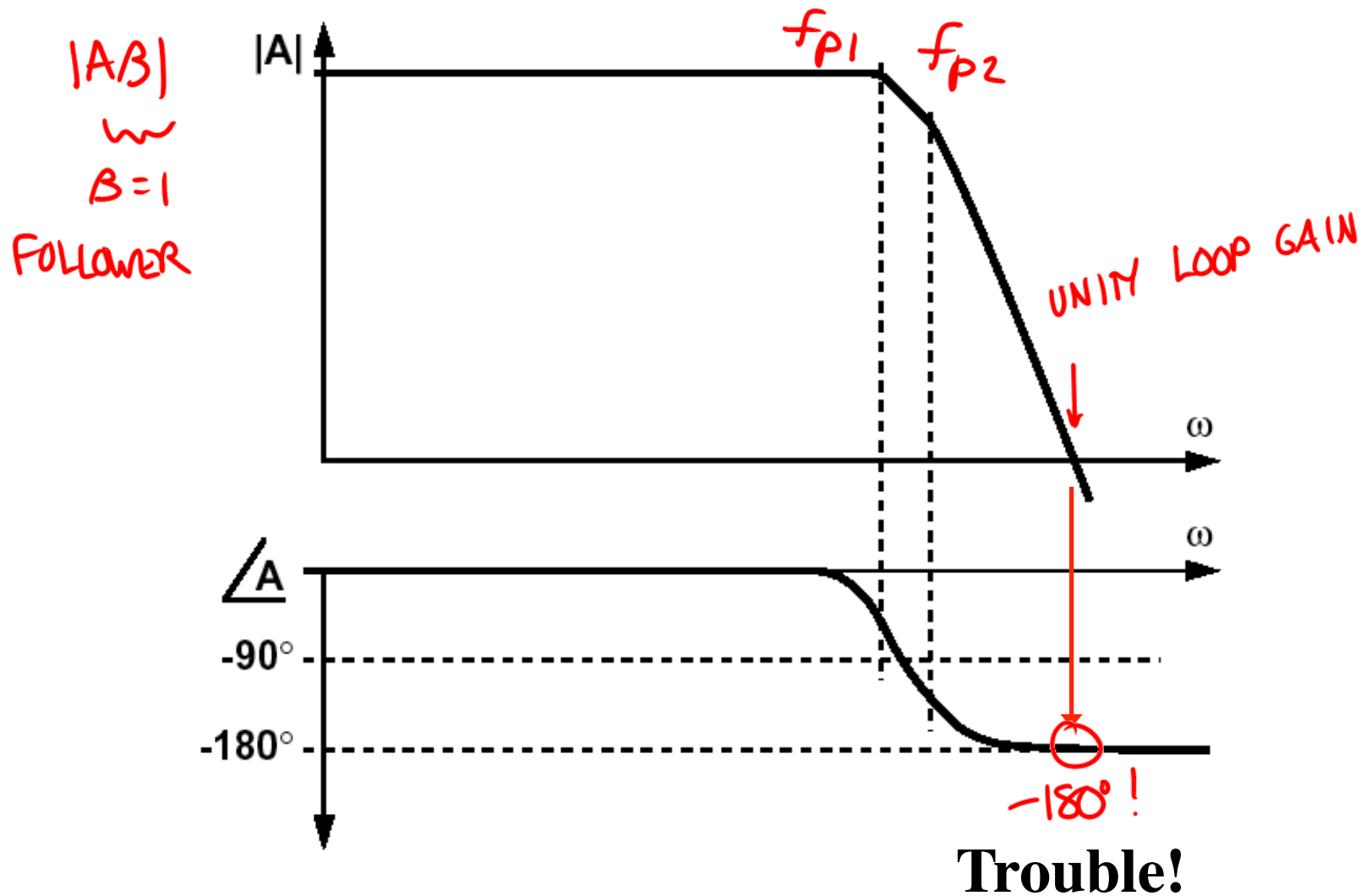
$$|A\beta| = 1 \text{ AND } \angle A\beta = -180^\circ$$

- Easier to get from Bode plot

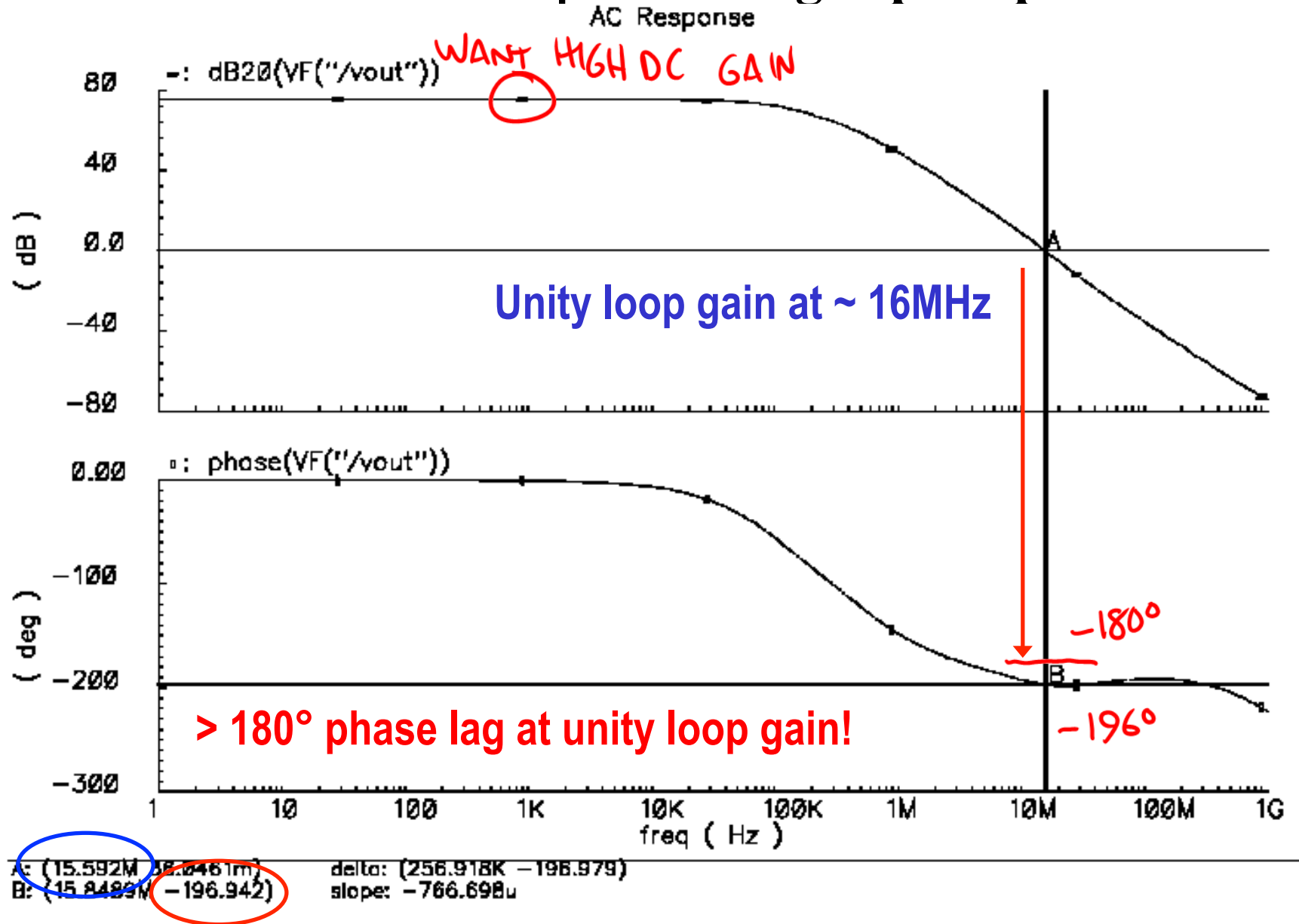


Look at original $A\beta$ for 2 stage op-amp

- Find ω at which $|A\beta| = 1$; Check $\angle A\beta = -180^\circ$?



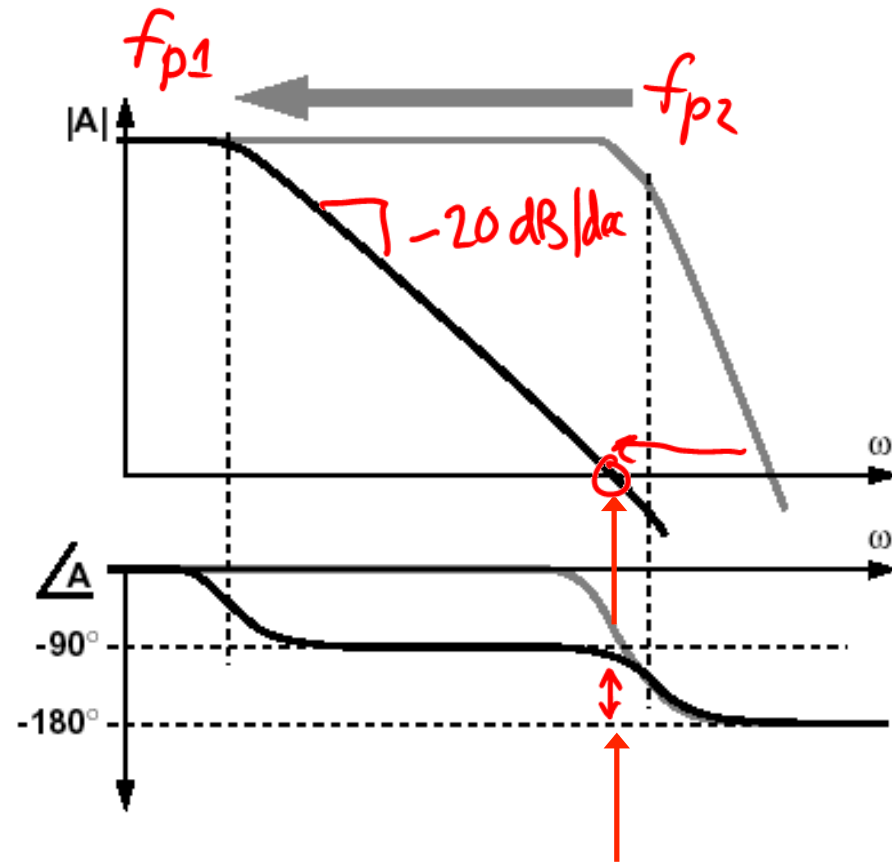
Simulation $A\beta$ for 2 stage op-amp



- Causes closed-loop instability

Compensation: “Dominant Pole”

- Move one pole to lower frequency
- How?

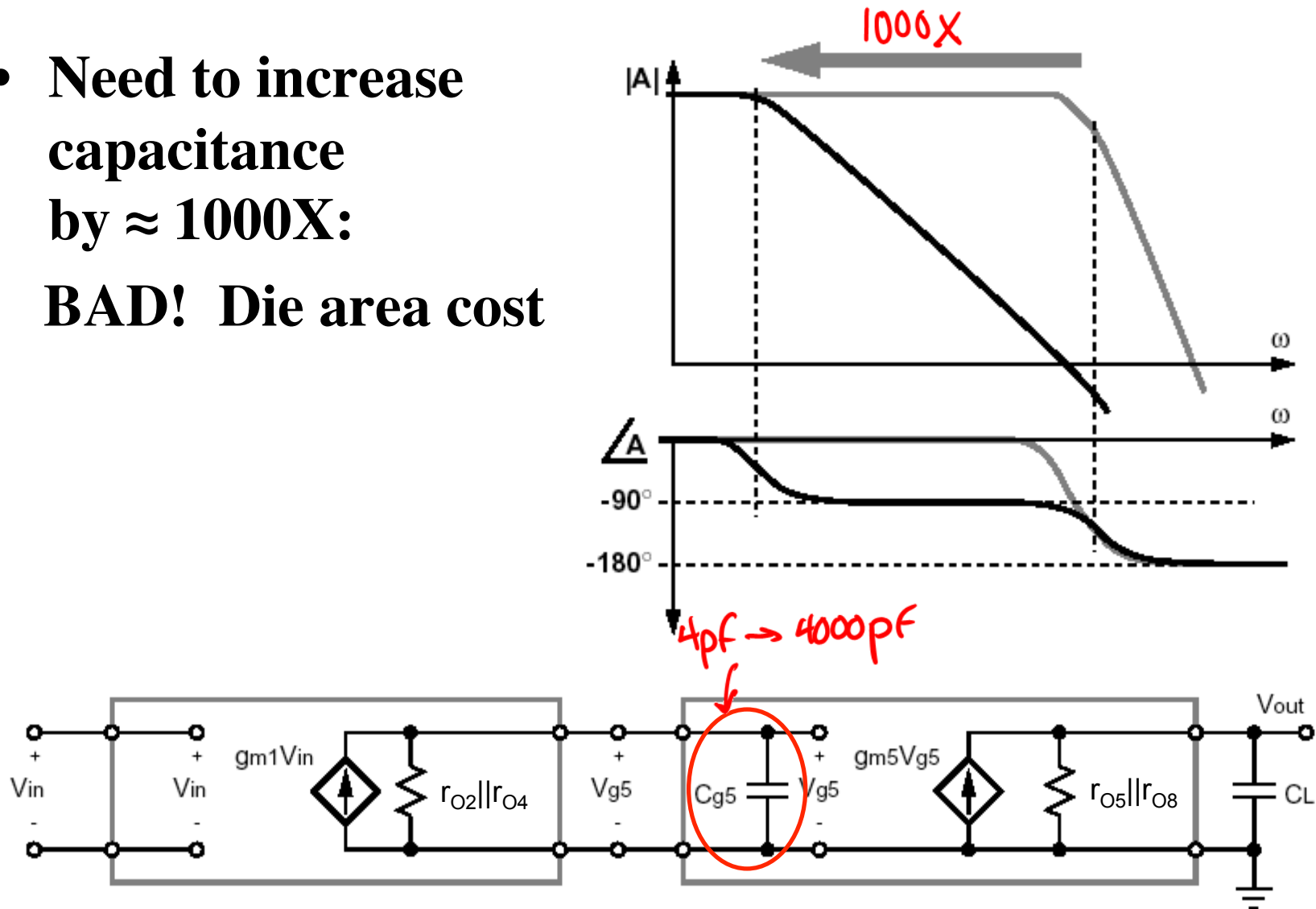


Move unity loop gain frequency f_T to lower value

So accumulated phase lag at f_T hasn't reached -180°

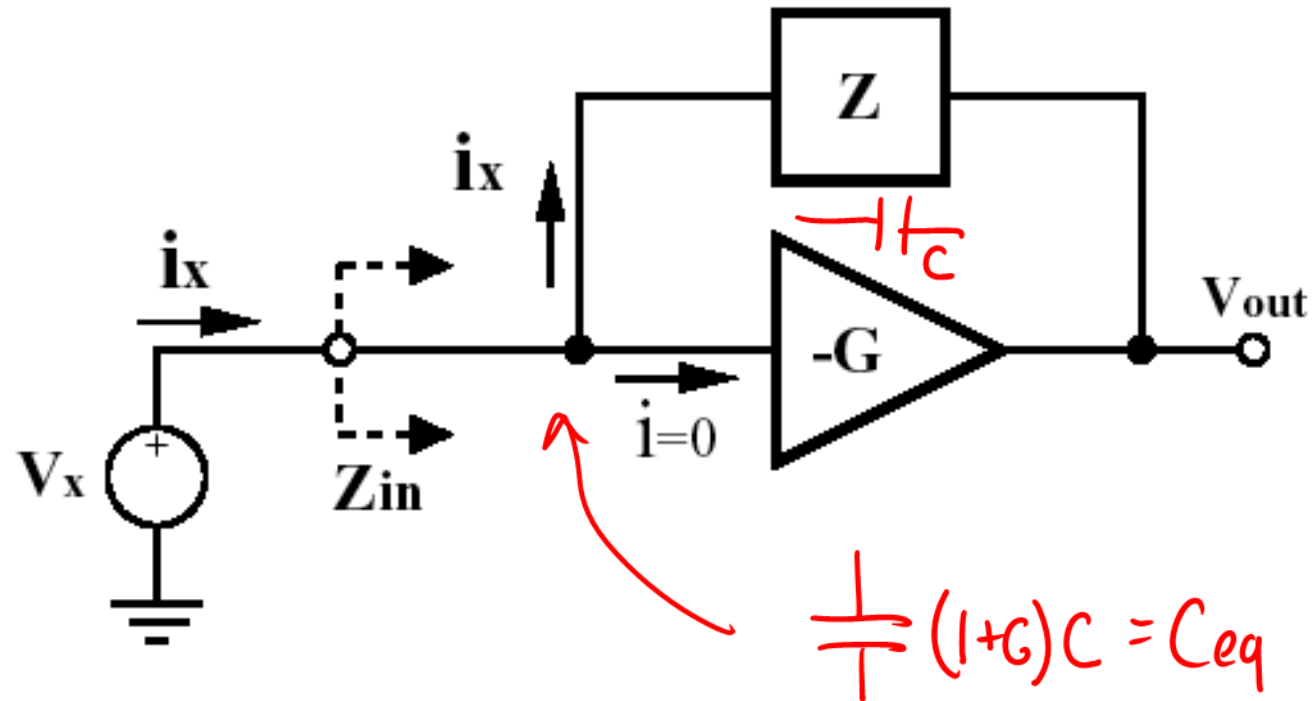
Compensation: “Dominant Pole”

- Need to increase capacitance by $\approx 1000\times$:
BAD! Die area cost



Miller Effect

- Impedance across inverting gain stage G
- Reduced by factor equal to $(1+G)$

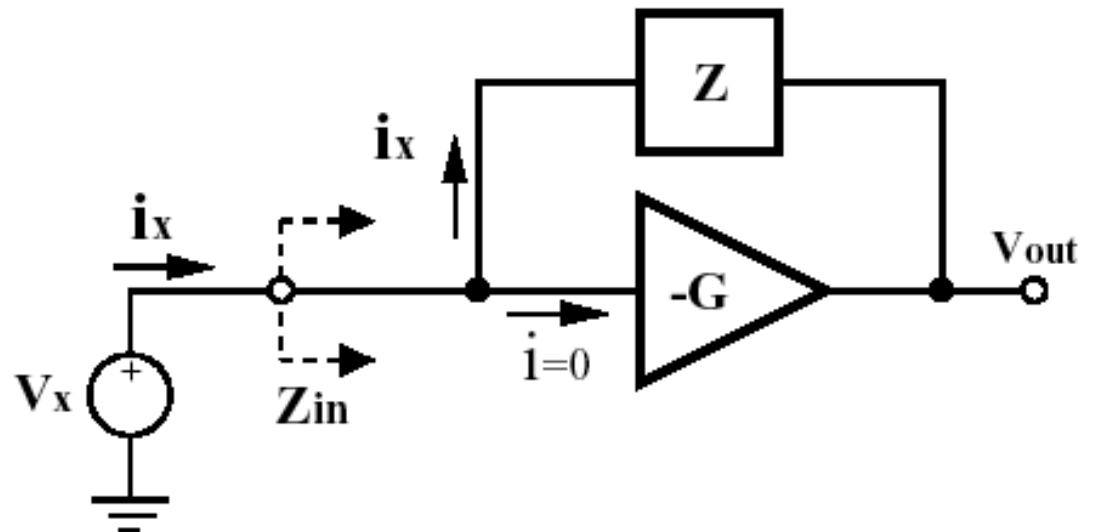


Math for Miller effect

$$i_x = \frac{v_x - (-Gv_x)}{Z}$$

$$i_x = \frac{v_x(1+G)}{Z}$$

$$\frac{v_x}{i_x} = Z_{in} = \frac{Z}{(1+G)}$$



- Impedance across inverting gain stage G
- Reduced by factor equal to $(1+G)$

Example: Impedance is capacitive

- Capacitance multiplied by (1+G)

$$Z_{in} = \frac{Z}{(1 + G)}$$

$$Z = \frac{1}{sC} \quad \rightarrow \quad Z_{in} = \frac{1}{s \underbrace{(1 + G)C}_{C_{eq}}}$$

- Equivalent capacitance higher by factor 1+G
- Problem for high bandwidth amplifiers
- Opportunity for compensation ...

Miller Compensation

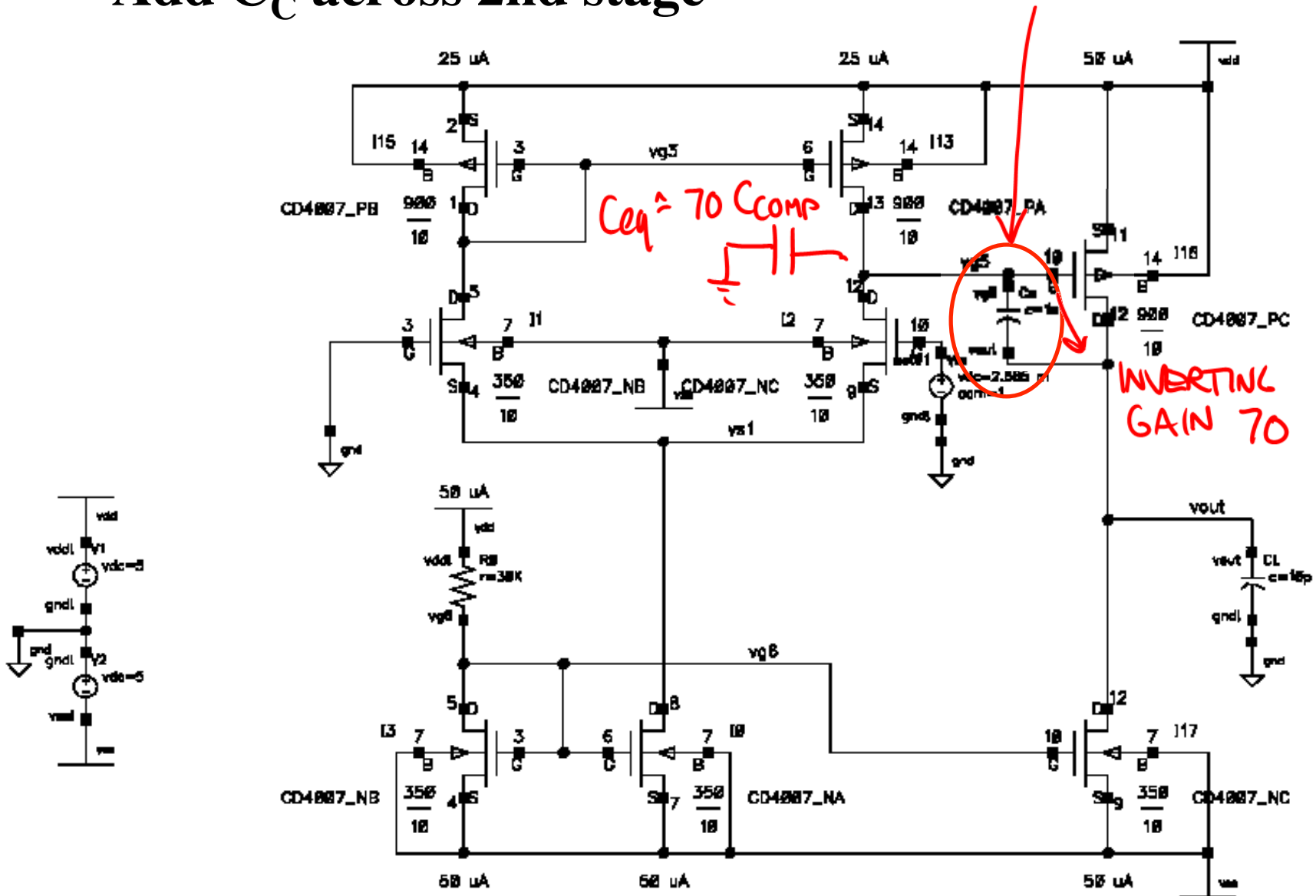
- **Need effect of large capacitance**
- **Use Miller effect to multiply small on-chip capacitance to higher effective value**
- **Effect of large capacitance without die area cost of large capacitance**



New schematic

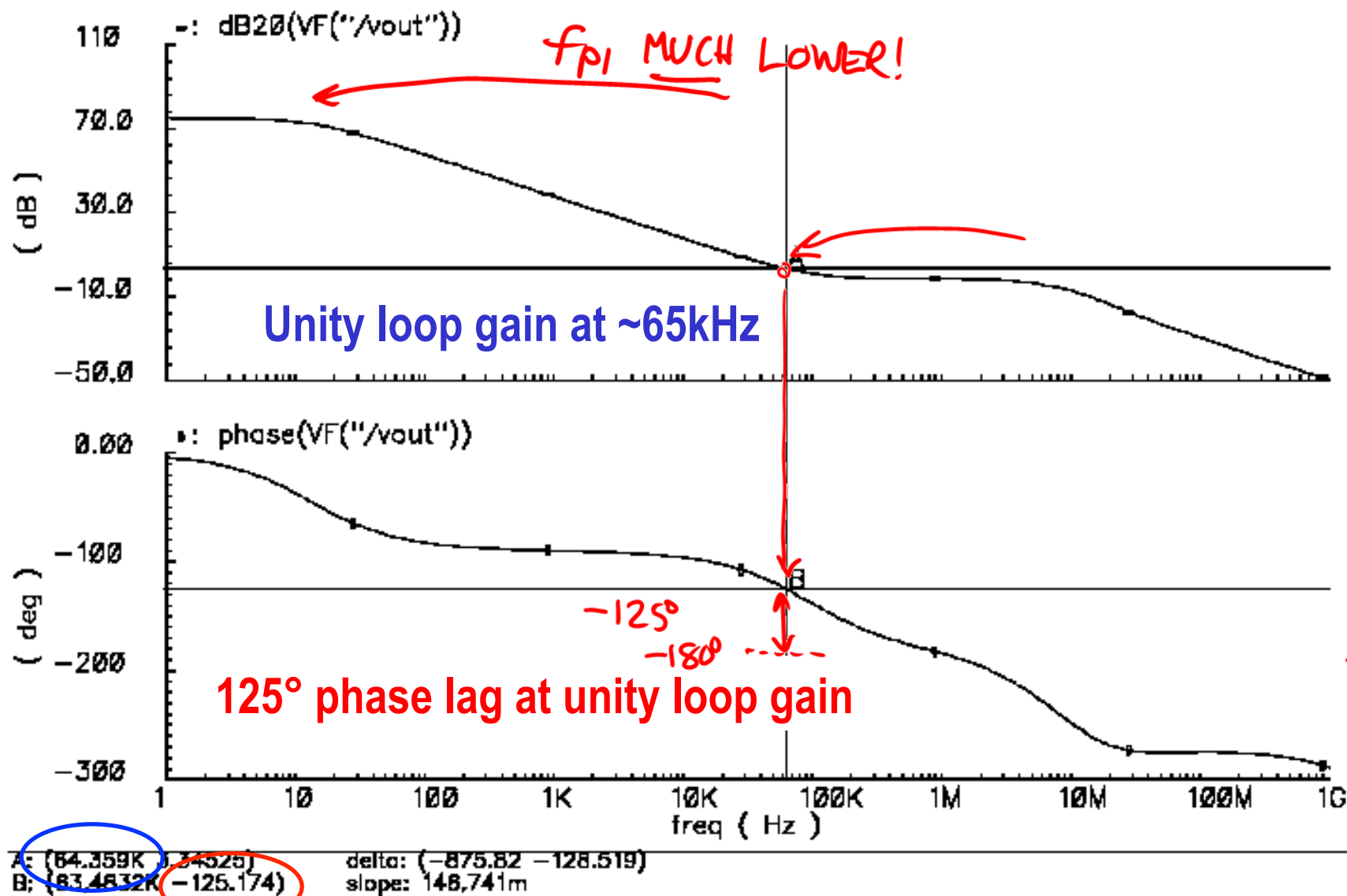
"COMPENSATION
CAPACITOR"

- Add C_C across 2nd stage



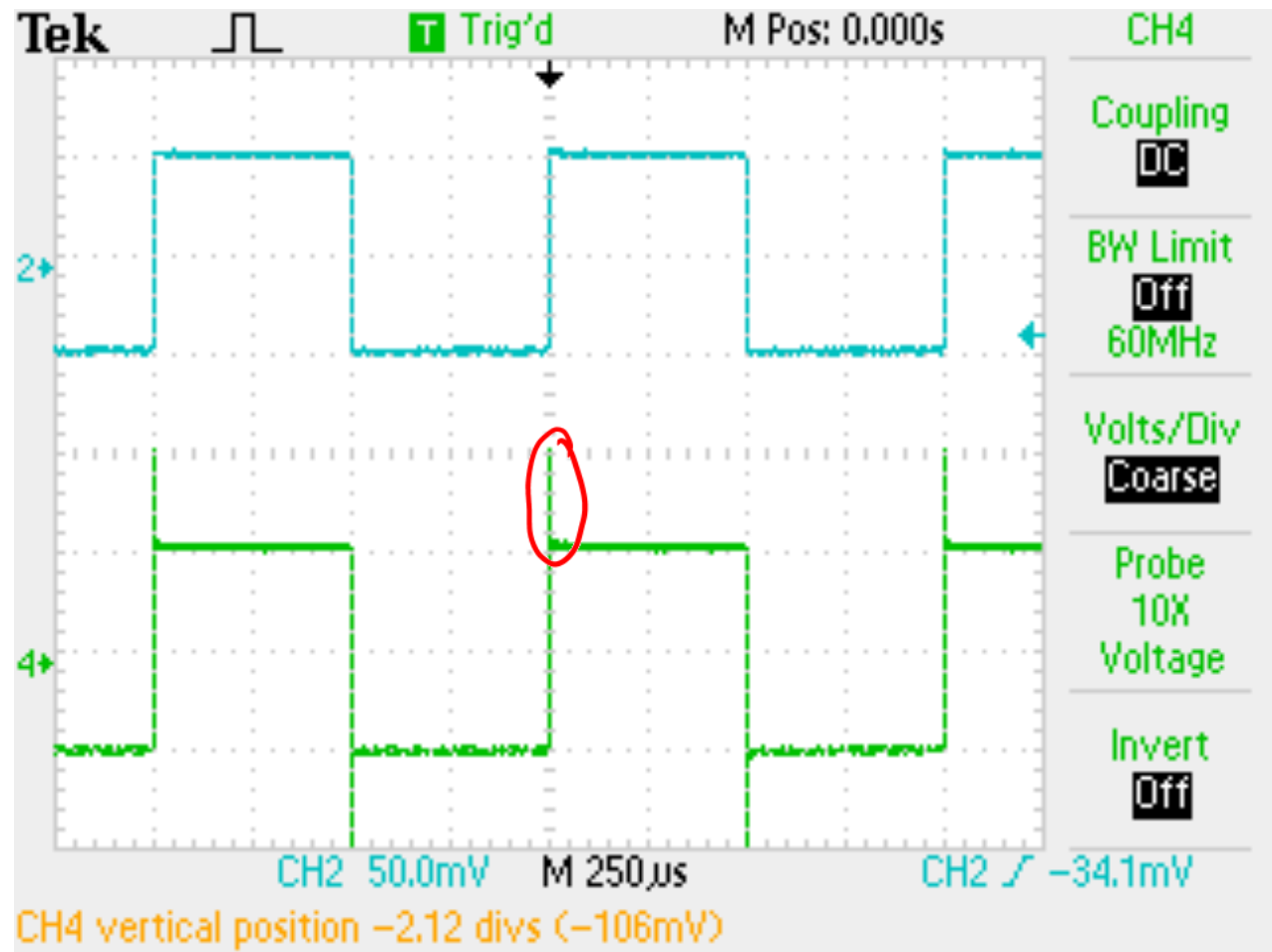
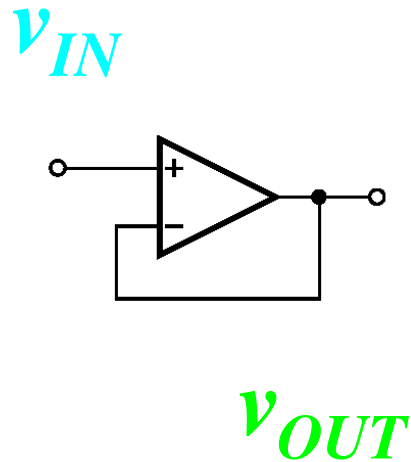
New loop gain transfer function

AC Response



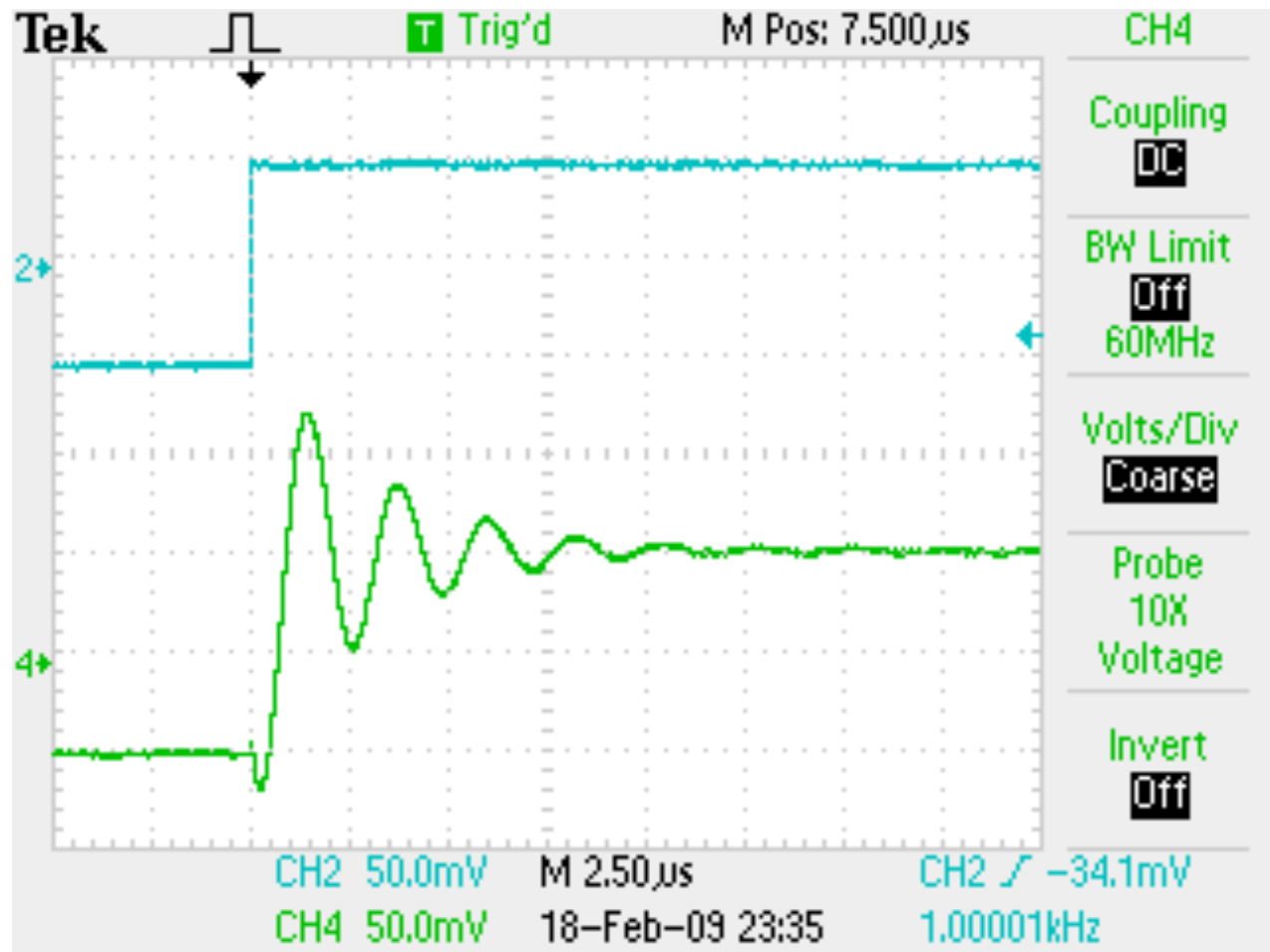
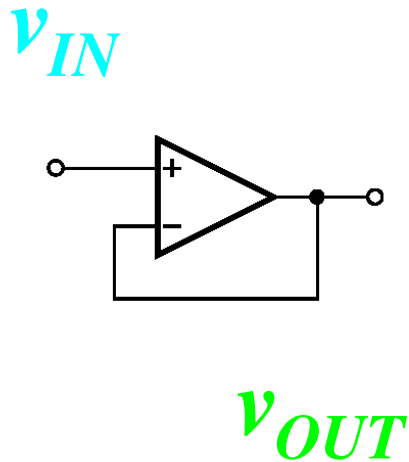
New step response

- No oscillation!



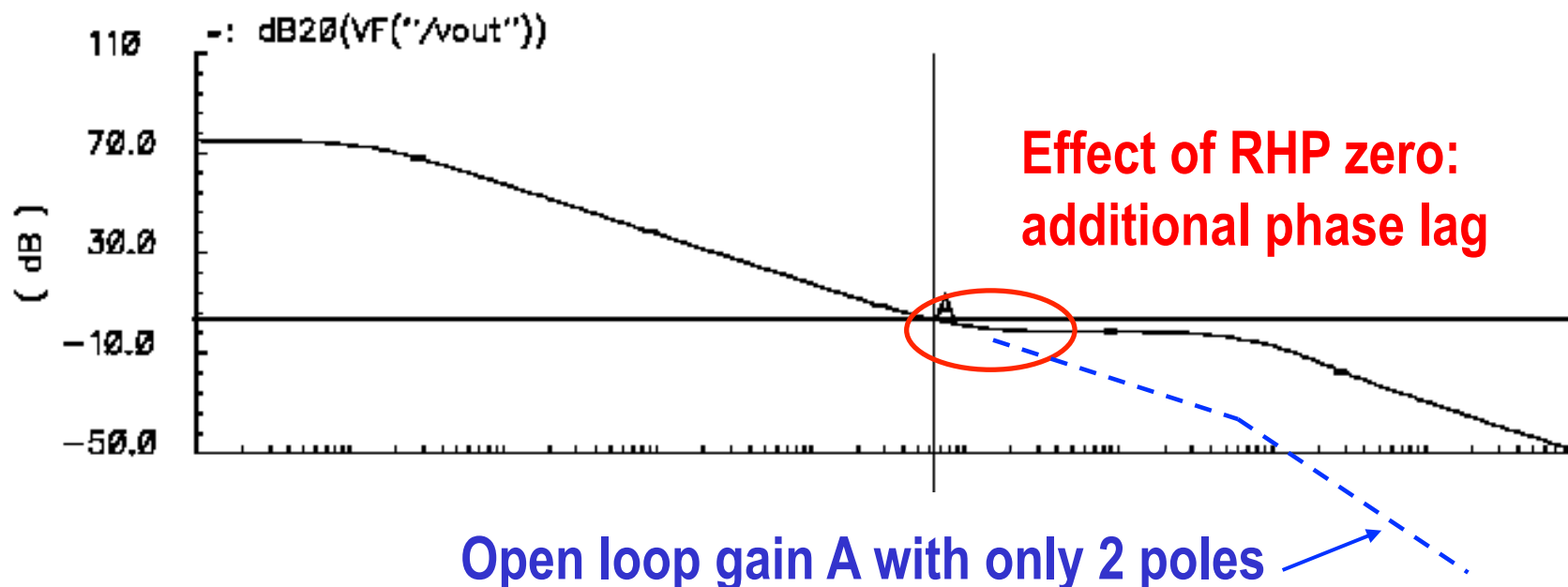
New step response with C_C

- Zoom in on small-signal step response:
Some overshoot and ringing



Reason: RHP zero in complete transfer function

AC Response



- Complete transfer function looks like:

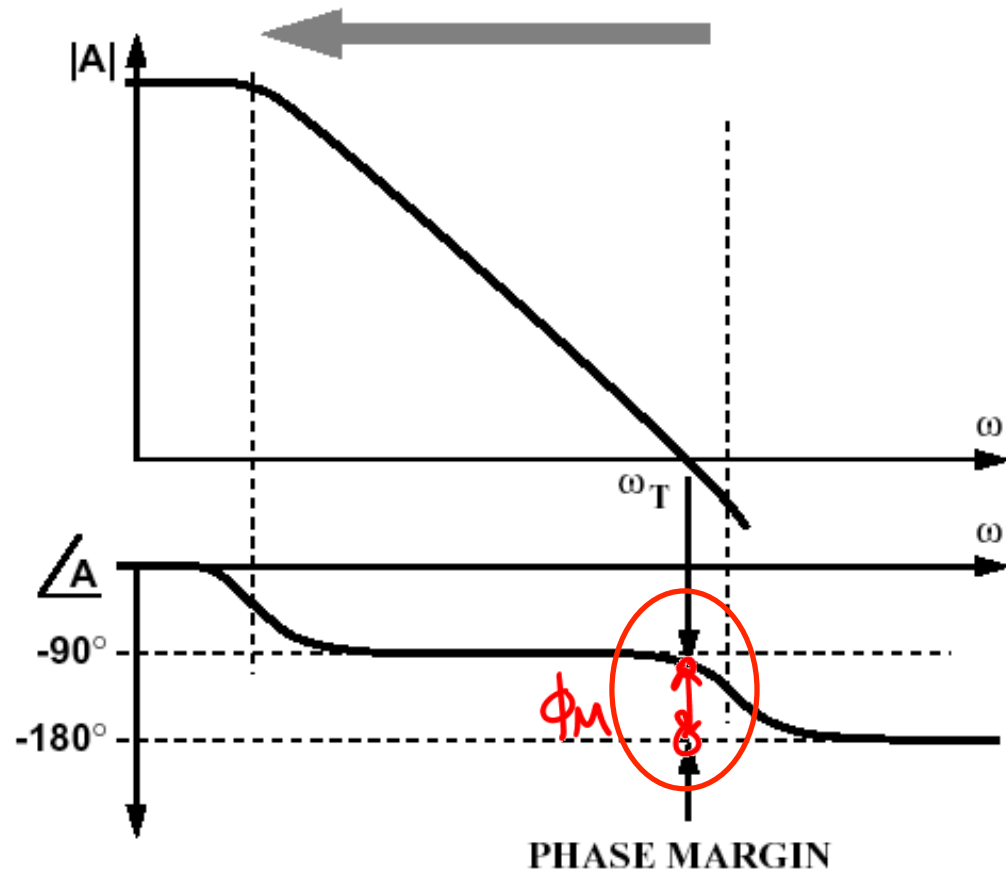
$$A(j\omega) = \frac{A_0 [1 - j(\omega/\omega_Z)]}{[1 + j(\omega/\omega_{p1})][1 + j(\omega/\omega_{p2})]}$$

RHP ZERO NOT IN SIMPLE MODEL

- See Razavi 10.5, Johns & Martin 5.2

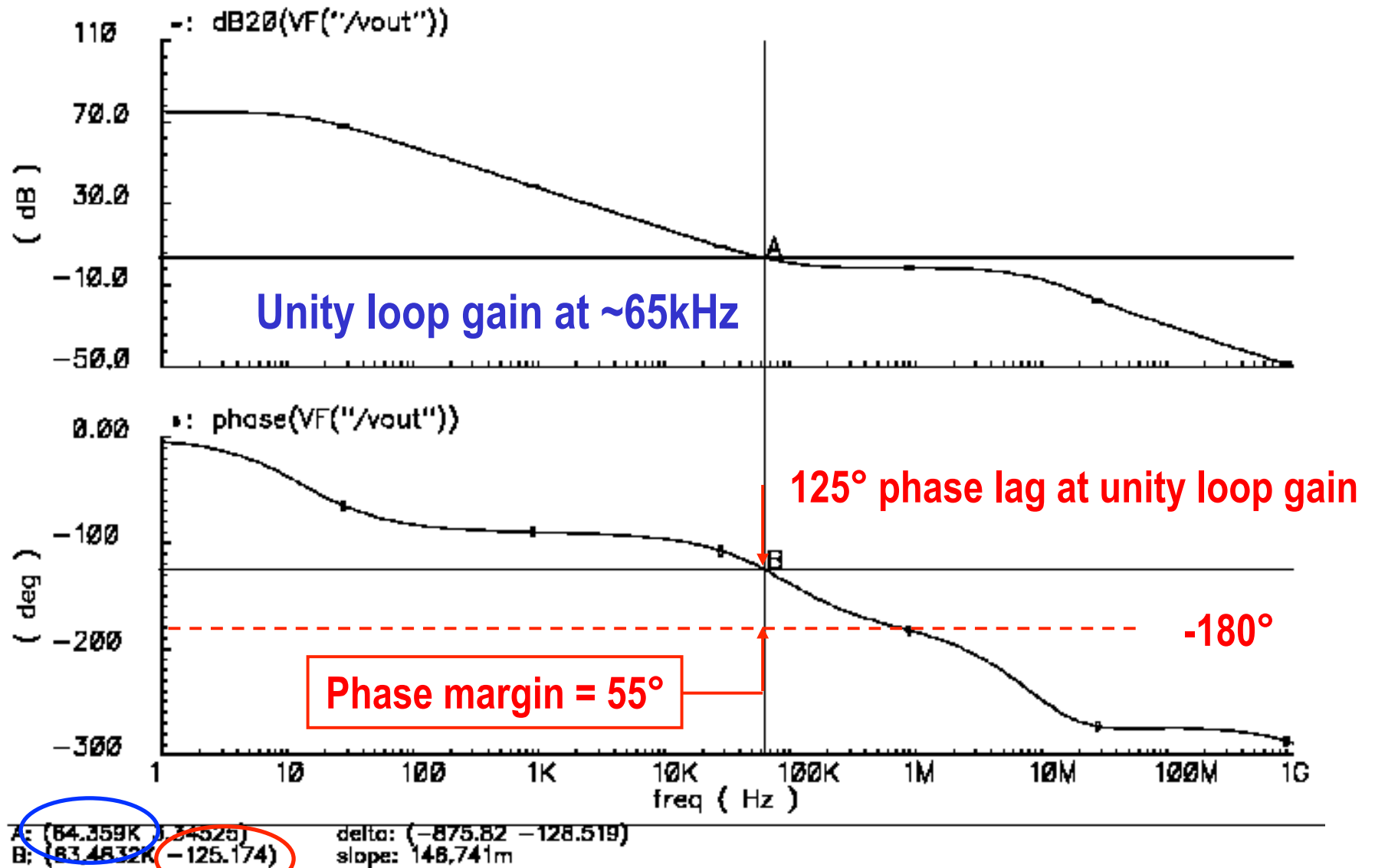
"Phase margin"

- How stable is new transfer function?
- Phase margin =
Phase lag at $|A\beta| = 1$
minus (-180°)
- Usually want at least 60° for stable step response



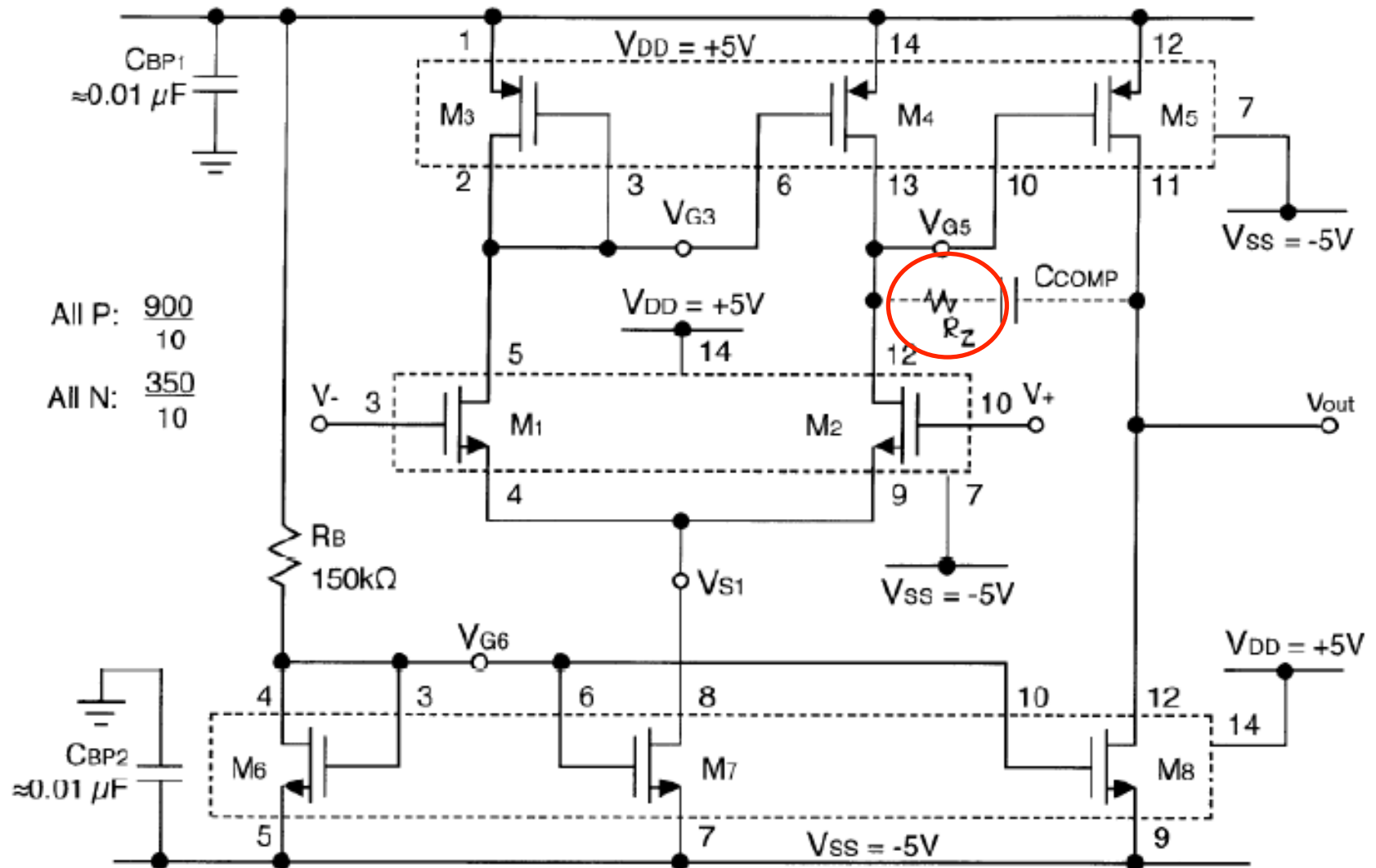
Phase margin of op-amp with C_r

AC Response



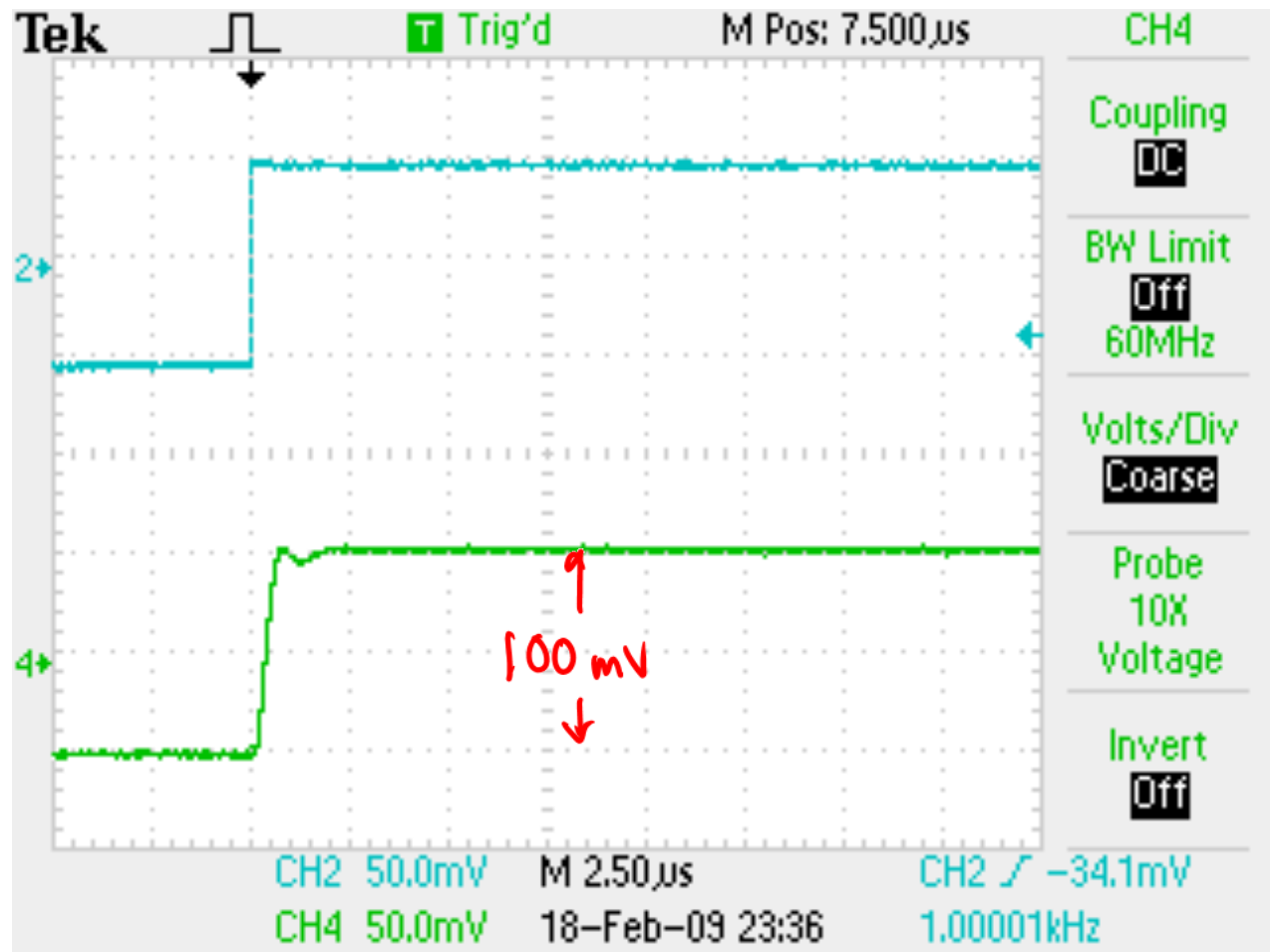
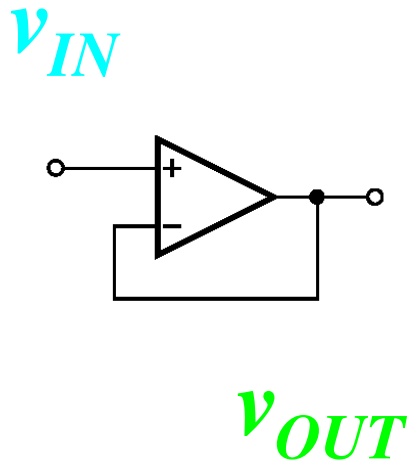
Solution to RHP zero problem

- Add R_Z in series with C_C
Moves RHP zero to much higher frequency



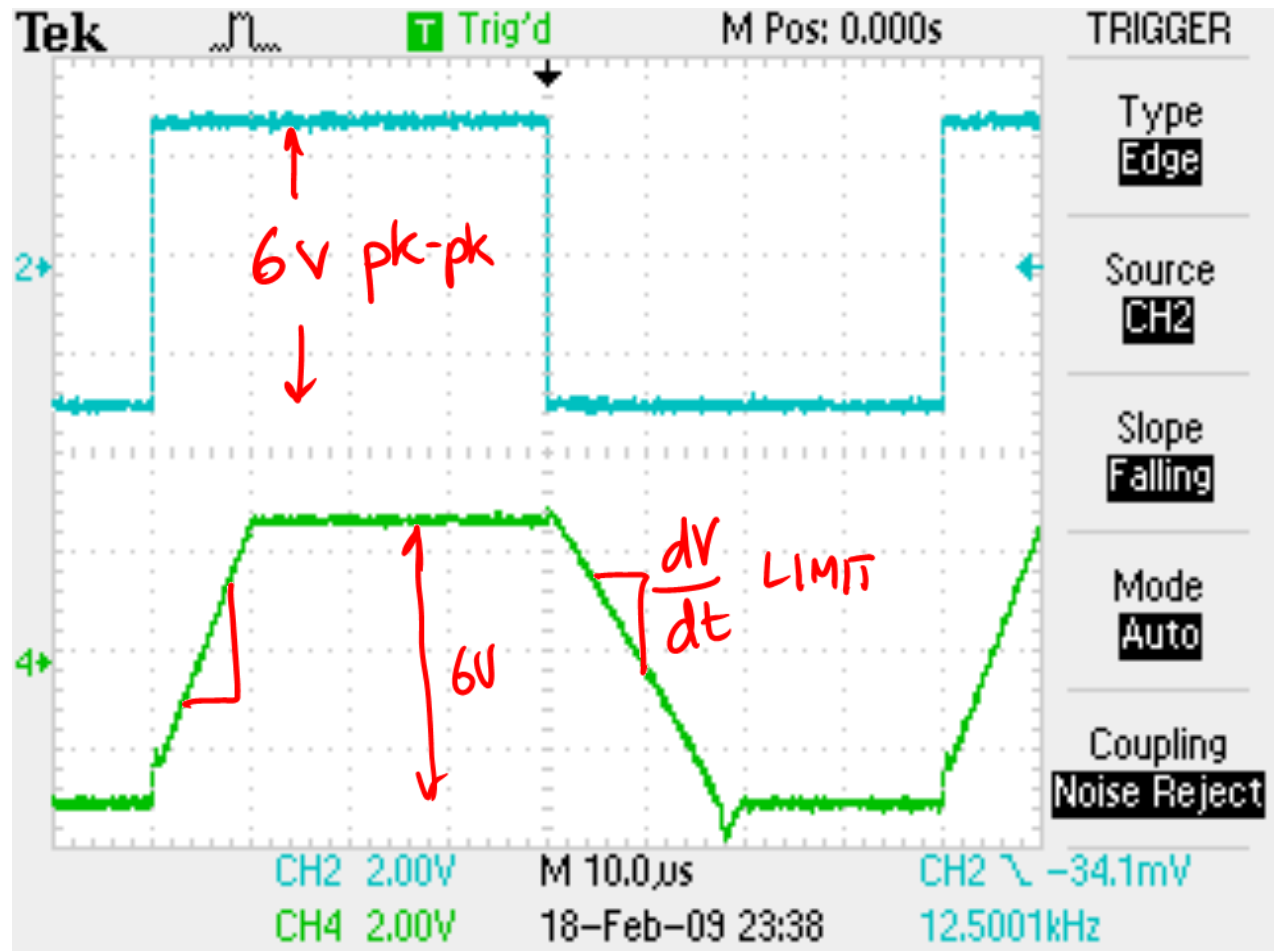
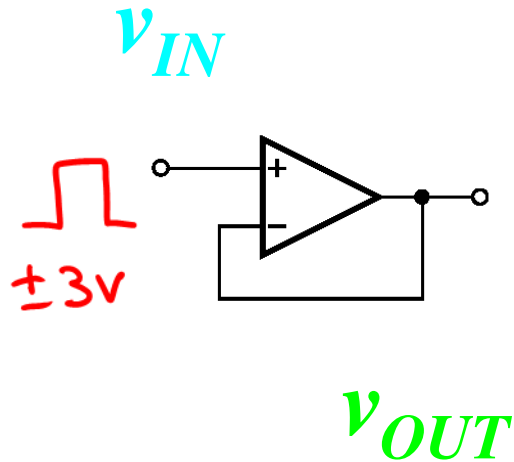
New step response with R_Z , C_C

- Zoom in on small-signal step response:
No overshoot, ringing: phase margin improved



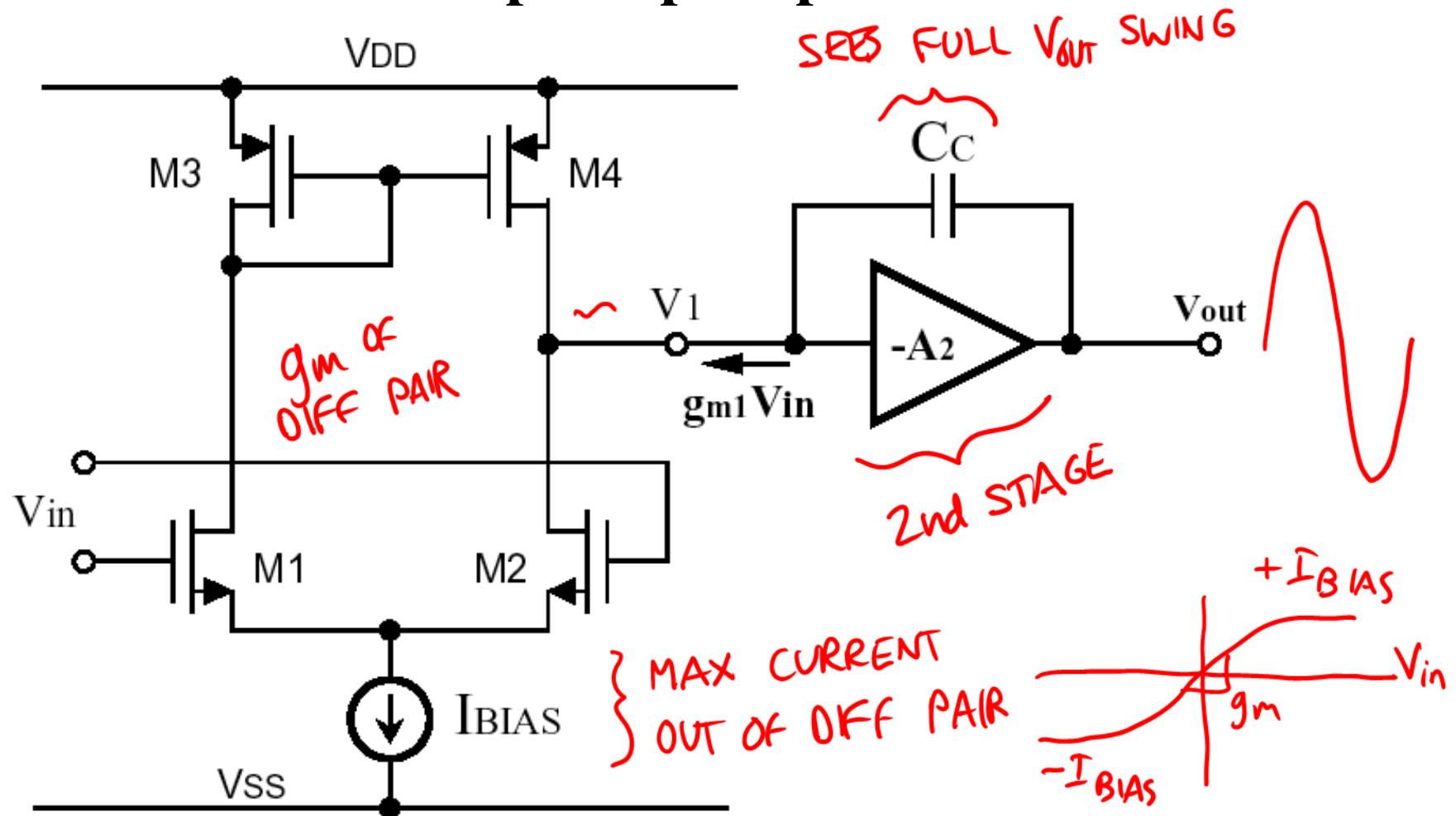
Large signal step response

- Slew Rate Limiting!?!



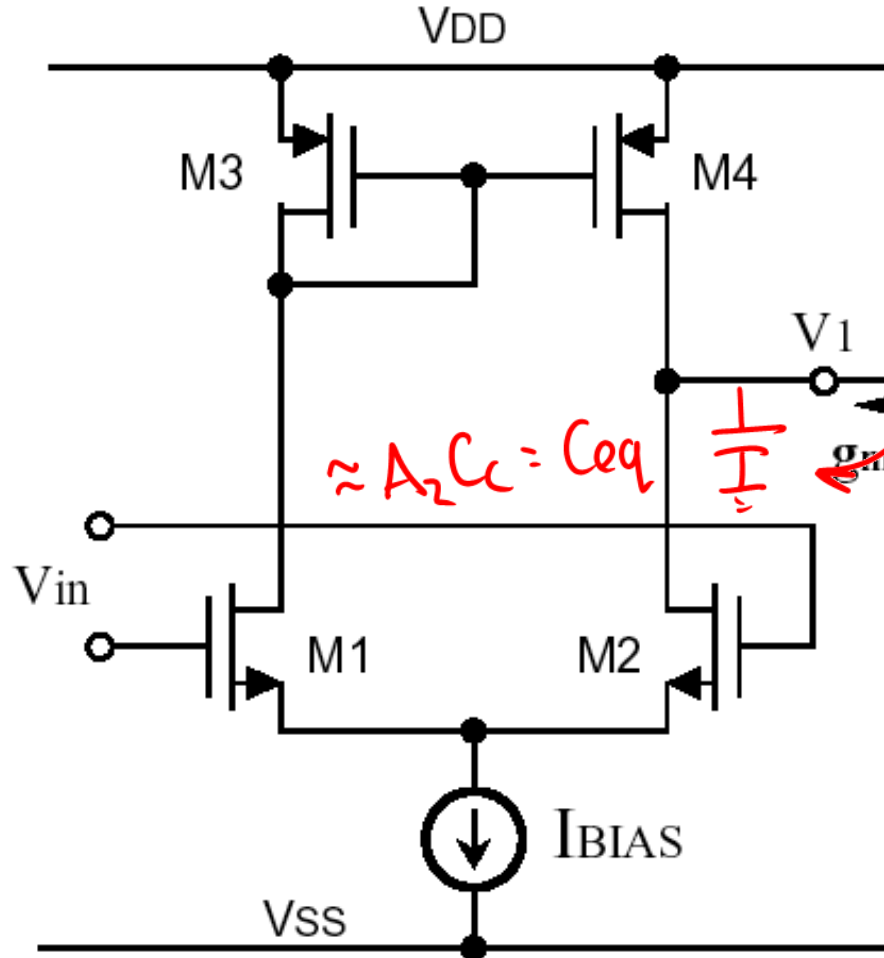
See Solomon op-amp paper for model; rising/falling asymmetry

Dominant pole op-amp model



- Simpler model with dominant pole from C_c

Approximate dominant pole transfer function



$$\approx A_2 C_c = C_{eq}$$

$$\frac{1}{s}$$

$$g_{m1} V_{in}$$

DC GAIN

$$|A(j\omega)| \approx \frac{g_{m1}(r_{o2} \parallel r_{o4}) A_2}{[1 + j\omega(r_{o2} \parallel r_{o4}) A_2 C_c]}$$

Miller multiplied C_c

$$A_2 = g_{m5}(r_{o5} \parallel r_{o8})$$

2nd stage gain

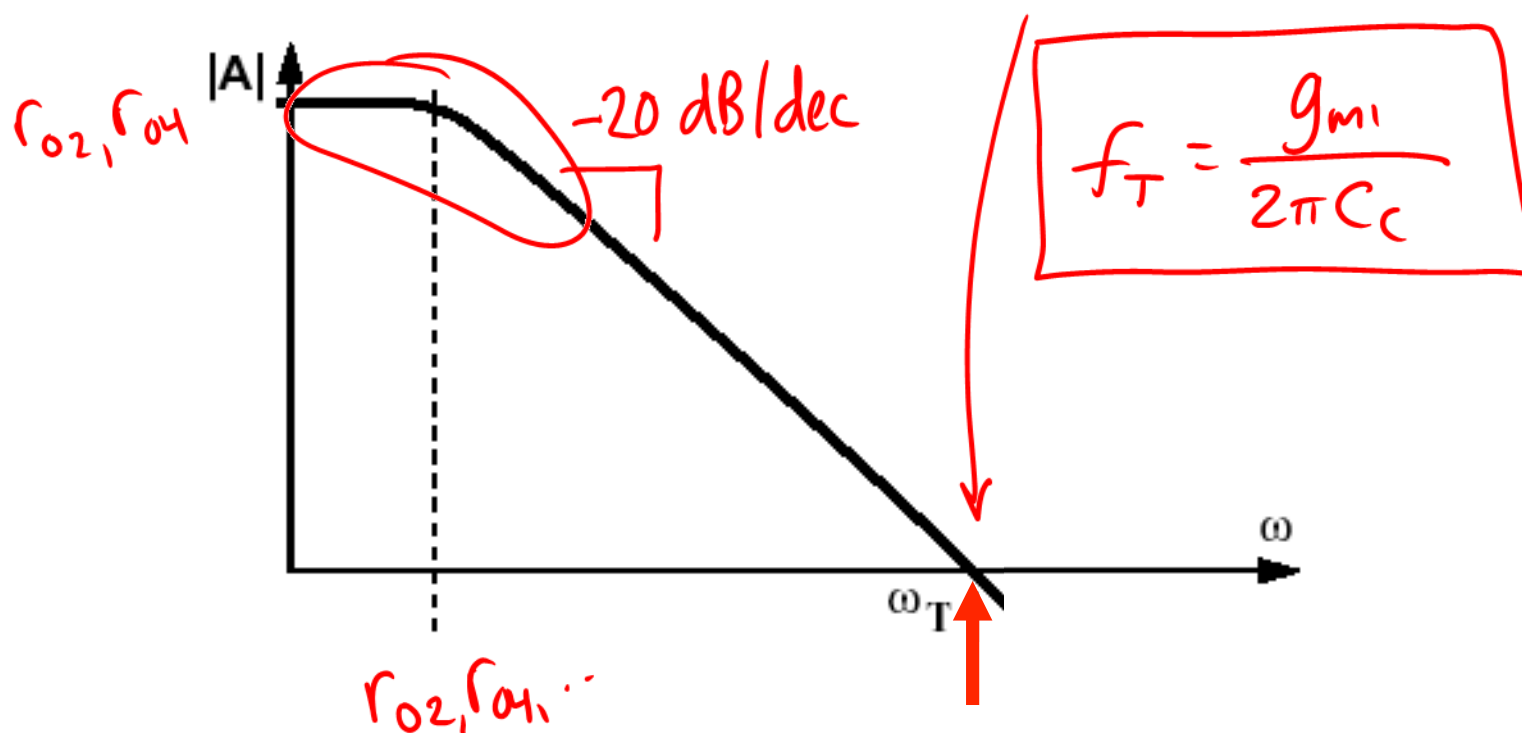
Unity gain frequency

- Depends only on
 - Input stage transconductance g_{m1}
 - Compensation capacitor C_C

$$|A(j\omega)| \approx \frac{g_{m1}(r_{O2} \parallel r_{O4})A_2}{\omega(r_{O2} \parallel r_{O4})A_2C_C}$$

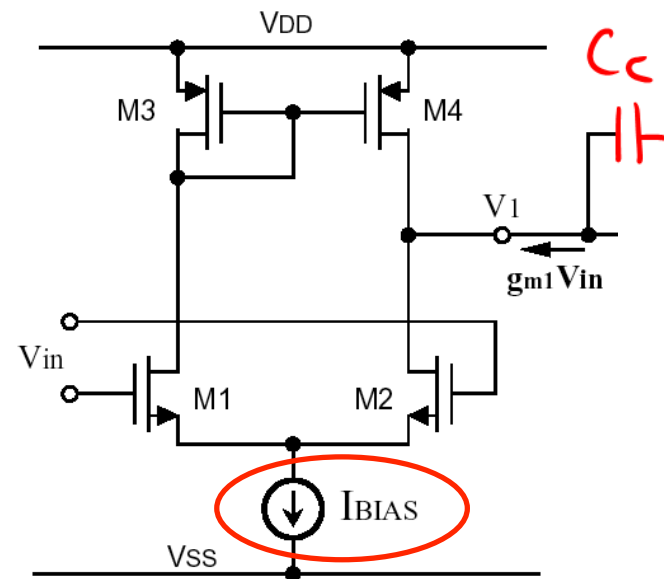
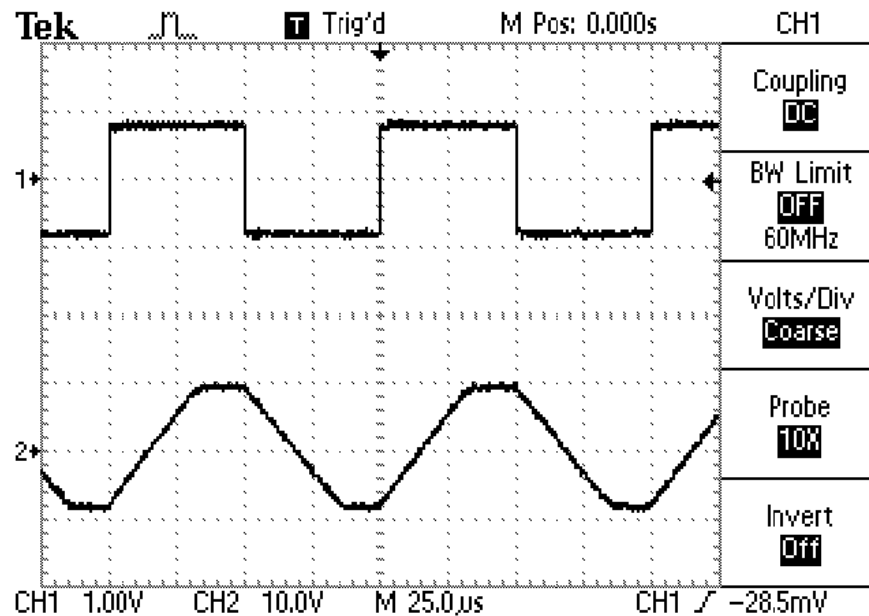
$$|A(j\omega)| = 1 \quad \text{at} \quad \omega_T$$

$$\omega_T \approx \frac{g_{m1}}{C_C}$$



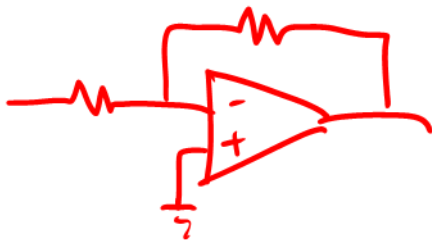
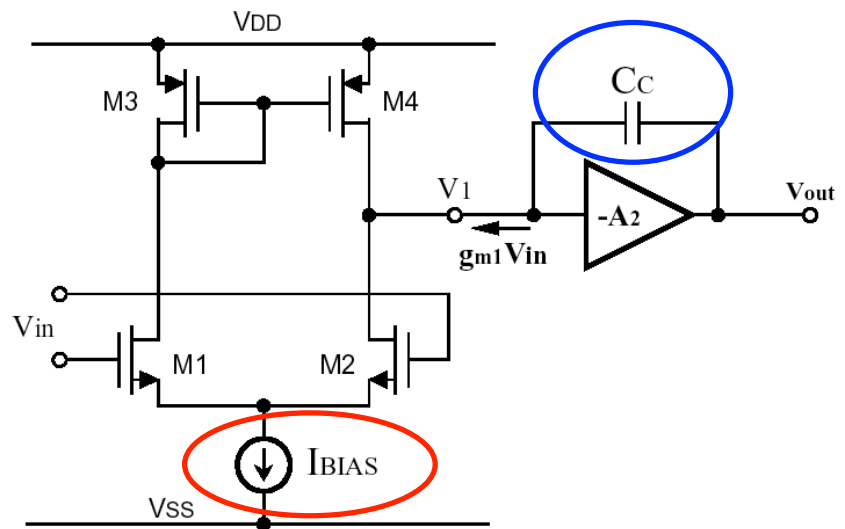
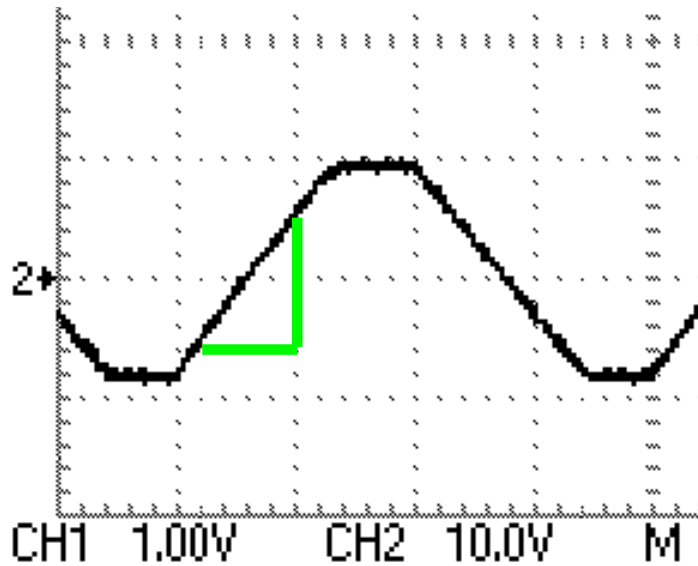
Slew rate

- $I = C \, dV/dt$
- Only limited current I_{BIAS} available to charge, discharge C_C



Slew rate

- $$I = C \frac{dV}{dt} \Rightarrow \frac{dV}{dt} = \frac{I_{BIAS}}{C_C}$$



Summary Op-amp:

- **Stability**
- **Compensation**
- **Miller effect**
- **Phase Margin**
- **Unity gain frequency**
- **Slew Rate Limiting**